Unification in Description Logics Part II: Unification in the DL \mathcal{EL}

Oliver Fernández Gil

Chair of Automata Theory



ESSLLI'19

Riga, August 2019

The lightweight DL \mathcal{EL}

• Fragment of \mathcal{ALC} :

$C ::= \top \mid A \mid C \sqcap C \mid \exists r.C$

The lightweight DL \mathcal{EL}

• Fragment of \mathcal{ALC} :

$C ::= \top \mid A \mid C \sqcap C \mid \exists r.C$

• Subsumption is polynomial, even w.r.t. general TBoxes [BBL05].

The lightweight DL \mathcal{EL}

• Fragment of \mathcal{ALC} :

$C ::= \top \mid A \mid C \sqcap C \mid \exists r.C$

• Subsumption is polynomial, even w.r.t. general TBoxes [BBL05].

• Underlies the OWL 2 EL profile and can be used to define large biomedical ontologies, such as SNOMED CT.

Characterization of equivalence

Characterization of equivalence

 \mathcal{EL} concept descriptions C can be translated into an equivalent reduced form C^r :

Characterization of equivalence

 \mathcal{EL} concept descriptions C can be translated into an equivalent reduced form C^r :

Apply the rewrite rule $C \sqcap D \rightarrow C$ if $C \sqsubseteq D$ (as long as possible).

Characterization of equivalence

 \mathcal{EL} concept descriptions C can be translated into an equivalent reduced form C^r :

Apply the rewrite rule $C \sqcap D \rightarrow C$ if $C \sqsubseteq D$ (as long as possible).

Theorem 4 [Küs01]

In \mathcal{EL} , $C \equiv D$ iff $C^r = D^r$ (modulo associativity/commutativity of \Box).

Characterization of equivalence

 \mathcal{EL} concept descriptions C can be translated into an equivalent reduced form C^r :

Apply the rewrite rule $C \sqcap D \rightarrow C$ if $C \sqsubseteq D$ (as long as possible).

Theorem 4 [Küs01] In \mathcal{EL} , $C \equiv D$ iff $C^r = D^r$ (modulo associativity/commutativity of \Box).

Characterization of subsumption

Characterization of equivalence

 \mathcal{EL} concept descriptions C can be translated into an equivalent reduced form C^r :

Apply the rewrite rule $C \sqcap D \rightarrow C$ if $C \sqsubseteq D$ (as long as possible).

Theorem 4 [Küs01] In \mathcal{EL} , $C \equiv D$ iff $C^r = D^r$ (modulo associativity/commutativity of \Box).

Characterization of subsumption

Corollary 5 [BM10b]

Let C and D be

$$C = A_1 \sqcap \ldots \sqcap A_k \sqcap \exists r_1.C_1 \sqcap \ldots \sqcap \exists r_m.C_m, \text{ and } D = B_1 \sqcap \ldots \sqcap B_\ell \sqcap \exists s_1.D_1 \sqcap \ldots \sqcap \exists s_n.D_n, \text{ where }$$

 $A_1, \ldots, A_k, B_1, \ldots, B_\ell \in N_C$. Then $C \sqsubseteq D$ iff $\{B_1, \ldots, B_\ell\} \subseteq \{A_1, \ldots, A_k\}$ and for every $j, 1 \le j \le n$, there exists an $i, 1 \le i \le m$, such that $r_i = s_j$ and $C_i \sqsubseteq D_j$.

An \mathcal{EL} unification problem of type zero

$$\Gamma := \{ X \sqcap \exists r. Y \equiv^? \exists r. Y \}.$$

An \mathcal{EL} unification problem of type zero

$$\Gamma := \{ X \sqcap \exists r. Y \equiv^? \exists r. Y \}.$$

To show: every complete set of unifiers $\mathcal M$ of Γ is not minimal, i.e.,

 \mathcal{M} contains $\sigma \neq \gamma$ such that $\sigma \preceq \gamma$.

An \mathcal{EL} unification problem of type zero

$$\Gamma := \{ X \sqcap \exists r. Y \equiv^? \exists r. Y \}.$$

To show: every complete set of unifiers $\mathcal M$ of Γ is not minimal, i.e.,

```
\mathcal{M} contains \sigma \neq \gamma such that \sigma \preceq \gamma.
```

Proof sketch.

• It is easy to find "a" solution for Γ :

An \mathcal{EL} unification problem of type zero

$$\Gamma := \{ X \sqcap \exists r. Y \equiv^? \exists r. Y \}.$$

To show: every complete set of unifiers \mathcal{M} of Γ is not minimal, i.e.,

 \mathcal{M} contains $\sigma \neq \gamma$ such that $\sigma \preceq \gamma$.

Proof sketch.

• It is easy to find "a" solution for Γ :

$$\begin{array}{cccc} X \to \top & X \to \exists r. \top & X \to \exists r. A \\ Y \to Y & Y \to Y & Y \to A \end{array}$$

An \mathcal{EL} unification problem of type zero

$$\Gamma := \{ X \sqcap \exists r. Y \equiv ? \exists r. Y \}.$$

To show: every complete set of unifiers $\mathcal M$ of Γ is not minimal, i.e.,

 \mathcal{M} contains $\sigma \neq \gamma$ such that $\sigma \preceq \gamma$.

Proof sketch.

• It is easy to find "a" solution for Γ :

$$\begin{array}{cccc} X \to \top & X \to \exists r. \top & X \to \exists r. A \\ Y \to Y & Y \to Y & Y \to A \end{array}$$

• However, the green solution implies that $\mathcal M$ contains σ such that:

 $\sigma(X) \not\equiv \top$ and $\sigma(X) \not\equiv \exists r. \top$.

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• \mathcal{M} contains σ of the form:

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From σ , we build $\hat{\sigma}$ using a new variable Z:

$$\widehat{\sigma}(X) := \sigma(X) \sqcap \exists r_1. Z$$
 and $\widehat{\sigma}(Y) := \sigma(Y) \sqcap Z.$

• \mathcal{M} contains σ of the form:

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From
$$\sigma$$
, we build $\widehat{\sigma}$ using a new variable Z:
 $\widehat{\sigma}(X) := \sigma(X) \sqcap \exists r_1.Z$ and $\widehat{\sigma}(Y) := \sigma(Y) \sqcap Z$.

• One can prove the following about $\widehat{\sigma} :$

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From
$$\sigma$$
, we build $\hat{\sigma}$ using a new variable Z:
 $\hat{\sigma}(X) := \sigma(X) \sqcap \exists r_1.Z$ and $\hat{\sigma}(Y) := \sigma(Y) \sqcap Z$.

- One can prove the following about $\widehat{\sigma}$:
 - $\hat{\sigma}$ is also a unifier of Γ (characterization of \sqsubseteq),

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From
$$\sigma$$
, we build $\widehat{\sigma}$ using a new variable Z:
 $\widehat{\sigma}(X) := \sigma(X) \sqcap \exists r_1.Z$ and $\widehat{\sigma}(Y) := \sigma(Y) \sqcap Z$.

- One can prove the following about $\widehat{\sigma}$:
 - $\hat{\sigma}$ is also a unifier of Γ (characterization of \sqsubseteq),
 - $\widehat{\sigma} \preceq \sigma \ (Z \rightarrow C_1 \text{ and } D \sqsubseteq C_1)$,

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From
$$\sigma$$
, we build $\hat{\sigma}$ using a new variable Z:
 $\hat{\sigma}(X) := \sigma(X) \sqcap \exists r_1.Z$ and $\hat{\sigma}(Y) := \sigma(Y) \sqcap Z$.

- One can prove the following about $\widehat{\sigma}$:
 - $\hat{\sigma}$ is also a unifier of Γ (characterization of \sqsubseteq),
 - $\widehat{\sigma} \preceq \sigma \ (Z \rightarrow C_1 \text{ and } D \sqsubseteq C_1)$,
 - $\sigma \neq \hat{\sigma}$ (characterization of \equiv).

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From
$$\sigma$$
, we build $\widehat{\sigma}$ using a new variable Z:
 $\widehat{\sigma}(X) := \sigma(X) \sqcap \exists r_1.Z$ and $\widehat{\sigma}(Y) := \sigma(Y) \sqcap Z$.

- One can prove the following about $\hat{\sigma}$:
 - $\hat{\sigma}$ is also a unifier of Γ (characterization of \sqsubseteq),
 - $\widehat{\sigma} \preceq \sigma \ (Z \rightarrow C_1 \text{ and } D \sqsubseteq C_1)$,
 - $\sigma \neq \hat{\sigma}$ (characterization of \equiv).
- $\widehat{\sigma}$ need not be in \mathcal{M} , but:

• \mathcal{M} contains σ of the form:

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From
$$\sigma$$
, we build $\widehat{\sigma}$ using a new variable Z:
 $\widehat{\sigma}(X) := \sigma(X) \sqcap \exists r_1.Z$ and $\widehat{\sigma}(Y) := \sigma(Y) \sqcap Z$.

- One can prove the following about $\widehat{\sigma}$:
 - $\hat{\sigma}$ is also a unifier of Γ (characterization of \sqsubseteq),
 - $\widehat{\sigma} \preceq \sigma \ (Z \rightarrow C_1 \text{ and } D \sqsubseteq C_1)$,
 - $\sigma \neq \hat{\sigma}$ (characterization of \equiv).
- $\widehat{\sigma}$ need not be in \mathcal{M} , but:

there is $\tau \in \mathcal{M}$ s.t. $\tau \preceq \widehat{\sigma}$

$$\sigma(X) = \exists r_1. C_1 \sqcap \ldots \sqcap \exists r_n. C_n \quad (n > 0)$$

$$\sigma(Y) = D$$

• From
$$\sigma$$
, we build $\widehat{\sigma}$ using a new variable Z:
 $\widehat{\sigma}(X) := \sigma(X) \sqcap \exists r_1.Z$ and $\widehat{\sigma}(Y) := \sigma(Y) \sqcap Z$.

- One can prove the following about $\widehat{\sigma}$:
 - $\hat{\sigma}$ is also a unifier of Γ (characterization of \sqsubseteq),
 - $\widehat{\sigma} \preceq \sigma \ (Z \rightarrow C_1 \text{ and } D \sqsubseteq C_1)$,
 - $\sigma \neq \hat{\sigma}$ (characterization of \equiv).
- $\widehat{\sigma}$ need not be in \mathcal{M} , but:

$$\begin{array}{ccc} \text{there is } \tau \in \mathcal{M} \text{ s.t.} \\ \tau \preceq \widehat{\sigma} \end{array} \implies \begin{array}{ccc} \tau \preceq \widehat{\sigma} \preceq \sigma \\ \tau \neq \sigma \end{array}$$

Idea: reduce the propositional satisfiability problem to \mathcal{EL} -unification.

Idea: reduce the propositional satisfiability problem to $\mathcal{EL}\text{-unification}.$

SAT Problem

Instance:	A propositional formula φ in CNF: $\varphi = c_1 \land \ldots \land c_m$, where
	each c_i is a disjunction of literals.
Question:	Is there an assignment $t: Vars(arphi) o \{t,f\}$ satisfying $arphi ?$

Idea: reduce the propositional satisfiability problem to \mathcal{EL} -unification.

SAT Problem

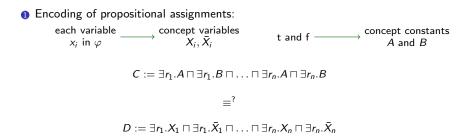
Instance:	A propositional formula φ in CNF: $\varphi = c_1 \land \ldots \land c_m$, where
	each c_i is a disjunction of literals.
Question:	Is there an assignment $t: Vars(arphi) o \{t,f\}$ satisfying $arphi?$

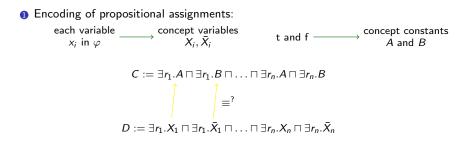
Given φ , we build an \mathcal{EL} -unification problem Γ_{φ} such that:

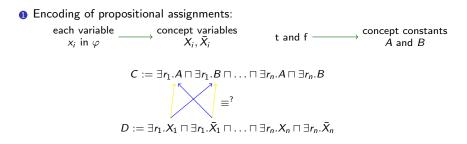
 φ is satisfiable if, and only if, Γ_φ has a unifier.

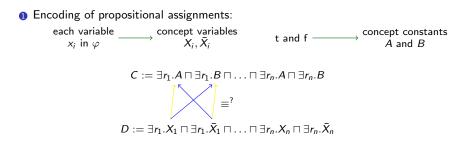
 $\begin{array}{c} \textbf{1} \quad \text{Encoding of propositional assignments:} \\ \begin{array}{c} \text{each variable} \\ x_i \text{ in } \varphi \end{array} \xrightarrow{} \begin{array}{c} \text{concept variables} \\ X_i, \bar{X}_i \end{array}$



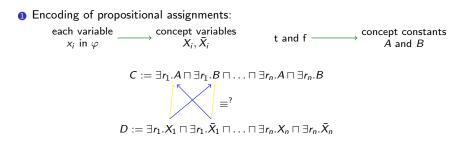






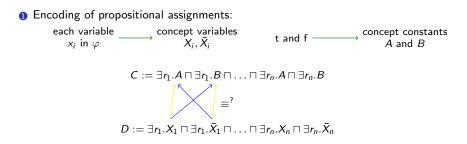


 $\sigma(C) \equiv \sigma(D)$ iff $(\sigma(X_i) = A \land \sigma(\bar{X}_i) = B)$ or $(\sigma(X_i) = B \land \sigma(\bar{X}_i) = A)$



$$\sigma(C) \equiv \sigma(D)$$
 iff $(\sigma(X_i) = A \land \sigma(\bar{X}_i) = B)$ or $(\sigma(X_i) = B \land \sigma(\bar{X}_i) = A)$

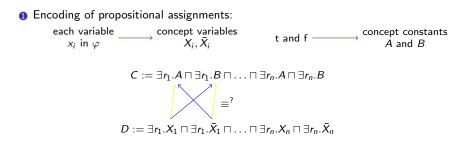
2 Simulate satisfiability of φ :



$$\sigma(C) \equiv \sigma(D)$$
 iff $(\sigma(X_i) = A \land \sigma(\bar{X}_i) = B)$ or $(\sigma(X_i) = B \land \sigma(\bar{X}_i) = A)$

2 Simulate satisfiability of φ :

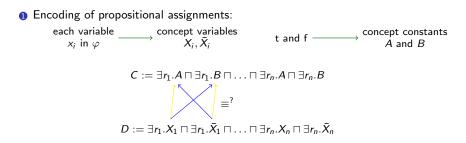
 $\begin{array}{cc} \text{each clause} & \text{concept pattern} \\ c_j = \ell_{j_1} \lor \ldots \lor \ell_{j_q} & \longrightarrow & P_j := Z_{j_1} \sqcap \ldots \sqcap Z_{j_q} \sqcap B \end{array}$



$$\sigma(C) \equiv \sigma(D) \text{ iff } (\sigma(X_i) = A \land \sigma(\bar{X}_i) = B) \text{ or } (\sigma(X_i) = B \land \sigma(\bar{X}_i) = A)$$

2 Simulate satisfiability of φ :

$$\begin{array}{c} \text{each clause} \\ c_j = \ell_{j_1} \lor \ldots \lor \ell_{j_q} \longrightarrow \\ \end{array} \begin{array}{c} \text{concept pattern} \\ P_j := Z_{j_1} \sqcap \ldots \sqcap Z_{j_q} \sqcap B \\ \widetilde{X}_{i_i} \text{ if } \ell_{j_p} = x_i \\ \widetilde{X}_{i_i} \text{ if } \ell_{j_p} = \neg x_i \end{array}$$



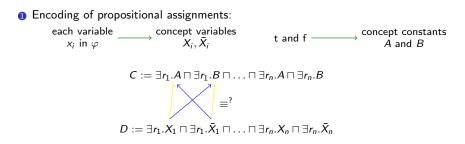
$$\sigma(C) \equiv \sigma(D)$$
 iff $(\sigma(X_i) = A \land \sigma(\bar{X}_i) = B)$ or $(\sigma(X_i) = B \land \sigma(\bar{X}_i) = A)$

2 Simulate satisfiability of φ :

each clause

$$c_j = \ell_{j_1} \lor \ldots \lor \ell_{j_q} \longrightarrow P_j := Z_{j_1} \sqcap \ldots \sqcap Z_{j_q} \sqcap B \quad Z_{j_p} = X_i, \text{ if } \ell_{j_p} = x_i$$

match
 $M := A \sqcap B$



$$\sigma(C) \equiv \sigma(D)$$
 iff $(\sigma(X_i) = A \land \sigma(\bar{X}_i) = B)$ or $(\sigma(X_i) = B \land \sigma(\bar{X}_i) = A)$

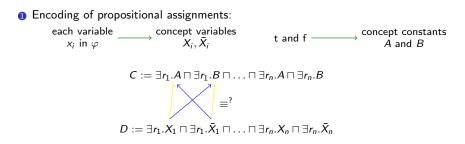
2 Simulate satisfiability of φ :

each clause

$$c_j = \ell_{j_1} \lor \ldots \lor \ell_{j_q} \longrightarrow \qquad P_j := Z_{j_1} \sqcap \ldots \sqcap Z_{j_q} \sqcap B \qquad Z_{j_p} = X_i, \text{ if } \ell_{j_p} = x_i$$

 $match \mid \qquad \bar{X}_i, \text{ if } \ell_{j_p} = \neg x_i$
 $M := A \sqcap B$

 $\sigma(P_j) \equiv \sigma(M)$ iff $\sigma(Z_{j_p}) = A$ for at least one $1 \le p \le q$.



$$\sigma(C) \equiv \sigma(D)$$
 iff $(\sigma(X_i) = A \land \sigma(\bar{X}_i) = B)$ or $(\sigma(X_i) = B \land \sigma(\bar{X}_i) = A)$

2 Simulate satisfiability of φ :

each clause

$$c_j = \ell_{j_1} \lor \ldots \lor \ell_{j_q} \longrightarrow P_j := Z_{j_1} \sqcap \ldots \sqcap Z_{j_q} \sqcap B \quad Z_{j_p} = X_i, \text{ if } \ell_{j_p} = x_i$$

match $\begin{vmatrix} X_i, \text{ if } \ell_{j_p} = \neg x_i \\ M := A \sqcap B \end{vmatrix}$ B's are important!

 $\sigma(P_j) \equiv \sigma(M)$ iff $\sigma(Z_{j_p}) = A$ for at least one $1 \le p \le q$.

2 Simulate satisfiability of φ :

$$C_{\varphi} := \exists s_1 . M \sqcap \ldots \sqcap \exists s_m . M$$
$$\equiv^?$$
$$P_{\varphi} := \exists s_1 . P_1 \sqcap \ldots \sqcap \exists s_m . P_m$$

2 Simulate satisfiability of φ :

$$C_{\varphi} := \exists s_1.M \sqcap \ldots \sqcap \exists s_m.M$$
$$\equiv^?$$
$$P_{\varphi} := \exists s_1.P_1 \sqcap \ldots \sqcap \exists s_m.P_m$$

 φ is satisfiable **iff** $C \sqcap C_{\varphi} \equiv D \sqcap P_{\varphi}$ is unifiable

2 Simulate satisfiability of φ :

$$C_{\varphi} := \exists s_1.M \sqcap \ldots \sqcap \exists s_m.M$$
$$\equiv^?$$

 $P_{\varphi} := \exists s_1.P_1 \sqcap \ldots \sqcap \exists s_m.P_m$

 φ is satisfiable **iff** $C \sqcap C_{\varphi} \equiv^{?} D \sqcap P_{\varphi}$ is unifiable

Theorem 6 [BK00]

EL-unification is NP-hard. Even for the special case of matching!

• Consider unification problems of the form: $\Gamma = \{ C_1 \sqsubset^? D_1, \dots, C_n \sqsubset^? D_n \}$

• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

• Restrict the attention to flat unification problems:

• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: A, $\exists r.A$ or $\exists r.\top$, where $A \in N_C$.

• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: A, $\exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

 $C_1 \sqcap \ldots \sqcap C_m \sqsubseteq$? *D*, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq$? *D*).

• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: A, $\exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

 $C_1 \sqcap \ldots \sqcap C_m \sqsubseteq^? D$, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq^? D)$.

• By introducing new variables, every Γ can be transformed into a flat Γ':

• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: A, $\exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

 $C_1 \sqcap \ldots \sqcap C_m \sqsubseteq$? *D*, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq$? *D*).

• By introducing new variables, every Γ can be transformed into a flat Γ' :

 $A \sqcap \exists r.(B \sqcap \exists s.Y) \sqsubseteq X \sqcap \exists s.B$

• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: A, $\exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

$$C_1 \sqcap \ldots \sqcap C_m \sqsubseteq^? D$$
, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq^? D)$.

• By introducing new variables, every Γ can be transformed into a flat Γ' :

$$A \sqcap \exists r.(B \sqcap \exists s.Y) \sqsubseteq^{?} X \sqcap \exists s.B$$
$$rule 1 \downarrow$$
$$A \sqcap \exists r.X' \sqsubseteq^{?} X \sqcap \exists s.B$$
$$X' \sqsubseteq^{?} B \sqcap \exists s.Y$$
$$B \sqcap \exists s.Y \sqsubseteq^{?} X'$$

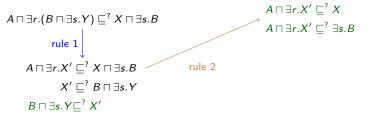
• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: $A, \exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

$$C_1 \sqcap \ldots \sqcap C_m \sqsubseteq^? D$$
, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq^? D)$.

• By introducing new variables, every Γ can be transformed into a flat Γ' :



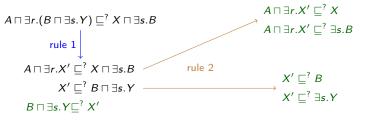
• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: $A, \exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

$$C_1 \sqcap \ldots \sqcap C_m \sqsubseteq^? D$$
, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq^? D)$.

• By introducing new variables, every Γ can be transformed into a flat Γ' :



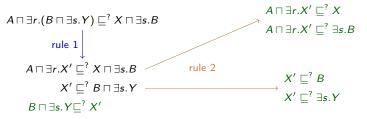
• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: $A, \exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

$$C_1 \sqcap \ldots \sqcap C_m \sqsubseteq^? D$$
, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq^? D)$.

• By introducing new variables, every Γ can be transformed into a flat Γ' :



The transformation is polynomial (time and size of Γ' w.r.t. Γ); and

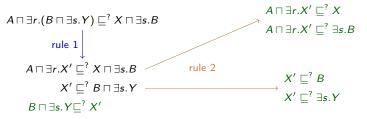
• Consider unification problems of the form:

$$\Gamma = \{C_1 \sqsubseteq^? D_1, \ldots, C_n \sqsubseteq^? D_n\}$$

- Restrict the attention to flat unification problems:
 - Atom: $A \in N_C$ or $\exists r.C$ Flat atom: $A, \exists r.A$ or $\exists r.\top$, where $A \in N_C$.
 - Flat unification problem: contains only subsumptions of the form:

$$C_1 \sqcap \ldots \sqcap C_m \sqsubseteq^? D$$
, where C_1, \ldots, C_m, D are flat $(m = 0 \Rightarrow \top \sqsubseteq^? D)$.

• By introducing new variables, every Γ can be transformed into a flat Γ':



• The transformation is polynomial (time and size of Γ' w.r.t. Γ); and

 Γ has a unifier **iff** Γ' is unifiable.

Idea of "in NP" upper bound:

Every unifiable flat \mathcal{EL} -unification problem has a local unifier.

Idea of "in NP" upper bound:

Every unifiable flat \mathcal{EL} -unification problem has a local unifier.

Local unifiers

Idea of "in NP" upper bound:

Every unifiable flat \mathcal{EL} -unification problem has a local unifier.

Local unifiers

Let Γ be a unification problem, N_v the variables in Γ and At_{nv} its non-variable atoms.

Idea of "in NP" upper bound:

Every unifiable flat \mathcal{EL} -unification problem has a local unifier.

Local unifiers

Let Γ be a unification problem, N_v the variables in Γ and At_{nv} its non-variable atoms.

$$\Gamma := \{Y \sqsubseteq^? \exists r.A, X \sqsubseteq^? \exists r.Y \sqcap \exists s.Y, \exists s.X \sqsubseteq \exists s.B\}$$

Idea of "in NP" upper bound:

Every unifiable flat \mathcal{EL} -unification problem has a local unifier.

Local unifiers

Let Γ be a unification problem, N_v the variables in Γ and At_{nv} its non-variable atoms.

$$\Gamma := \{Y \sqsubseteq^? \exists r.A, X \sqsubseteq^? \exists r.Y \sqcap \exists s.Y, \exists s.X \sqsubseteq \exists s.B\}$$

$$\mathsf{N}_{\mathsf{v}} = \{X, Y\} \qquad \mathsf{At}_{\mathsf{nv}} = \{A, B, \exists r. A, \exists s. B, \exists r. Y, \exists s. Y, \exists s. X\}$$

Idea of "in NP" upper bound:

Every unifiable flat $\mathcal{EL}\text{-unification}$ problem has a local unifier.

Local unifiers

Let Γ be a unification problem, N_v the variables in Γ and At_{nv} its non-variable atoms.

$$\Gamma := \{Y \sqsubseteq^? \exists r.A, X \sqsubseteq^? \exists r.Y \sqcap \exists s.Y, \exists s.X \sqsubseteq \exists s.B\}$$

$$\mathsf{N}_{\mathsf{v}} = \{X, Y\} \qquad \mathsf{At}_{\mathsf{nv}} = \{A, B, \exists r. A, \exists s. B, \exists r. Y, \exists s. Y, \exists s. X\}$$

• Consider assignments $S : N_v \to At_{nv}$

 $S(X) := \{B, \exists r. Y, \exists s. Y\}, \ S(Y) := \{\exists r. A\} \qquad S'(X) := \{B, \exists r. Y\}, \ S'(Y) := \{A, \exists s. X\}$

Idea of "in NP" upper bound:

Every unifiable flat \mathcal{EL} -unification problem has a local unifier.

Local unifiers

Let Γ be a unification problem, N_v the variables in Γ and At_{nv} its non-variable atoms.

$$\Gamma := \{Y \sqsubseteq^? \exists r.A, X \sqsubseteq^? \exists r.Y \sqcap \exists s.Y, \exists s.X \sqsubseteq \exists s.B\}$$

$$\mathsf{N}_{\mathsf{v}} = \{X, Y\} \qquad \mathsf{At}_{\mathsf{nv}} = \{A, B, \exists r. A, \exists s. B, \exists r. Y, \exists s. Y, \exists s. X\}$$

• Consider assignments $S : N_v \rightarrow At_{nv}$

 $S(X) := \{B, \exists r. Y, \exists s. Y\}, \ S(Y) := \{\exists r. A\} \qquad S'(X) := \{B, \exists r. Y\}, \ S'(Y) := \{A, \exists s. X\}$

• Every assignment S induces the following relation $>_S$ on N_v :

 $X >_S Y$ iff Y occurs in S(X).

Idea of "in NP" upper bound:

Every unifiable flat $\mathcal{EL}\text{-unification}$ problem has a local unifier.

Local unifiers

Let Γ be a unification problem, N_v the variables in Γ and At_{nv} its non-variable atoms.

$$\Gamma := \{Y \sqsubseteq^? \exists r.A, X \sqsubseteq^? \exists r.Y \sqcap \exists s.Y, \exists s.X \sqsubseteq \exists s.B\}$$

$$\mathsf{N}_{\mathsf{v}} = \{X, Y\} \qquad \mathsf{At}_{\mathsf{nv}} = \{A, B, \exists r. A, \exists s. B, \exists r. Y, \exists s. Y, \exists s. X\}$$

• Consider assignments $S : N_v \rightarrow At_{nv}$

 $S(X) := \{B, \exists r. Y, \exists s. Y\}, \ S(Y) := \{\exists r. A\} \qquad S'(X) := \{B, \exists r. Y\}, \ S'(Y) := \{A, \exists s. X\}$

• Every assignment S induces the following relation $>_S$ on N_v :

 $X >_S Y$ iff Y occurs in S(X).

$$X >_{S} Y \qquad \qquad X >_{S} Y, Y >_{S} X$$

• An assignment S is called acyclic if $>_{S}^{+}$ is irreflexive

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

• Any acyclic assignment S induces a substitution σ_S :

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

• Any acyclic assignment S induces a substitution σ_S : $S(X) := \{B, \exists r. Y, \exists s. Y\}, S(Y) := \{\exists r. A\}$ use $>_S^+$

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

• Any acyclic assignment *S* induces a substitution σ_S : $S(X) := \{B, \exists r. Y, \exists s. Y\}, S(Y) := \{\exists r. A\}$ use $>_S^+$

Y is minimal
$$\longrightarrow \sigma_{\mathcal{S}}(Y) := \prod_{D \in \mathcal{S}(Y)} D = \exists r.A$$

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

• Any acyclic assignment *S* induces a substitution σ_S : $S(X) := \{B, \exists r. Y, \exists s. Y\}, S(Y) := \{\exists r. A\}$ use $>_S^+$

Y is minimal
$$\longrightarrow \sigma_S(Y) := \prod_{D \in S(Y)} D = \exists r.A$$

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

• Any acyclic assignment *S* induces a substitution σ_S : $S(X) := \{B, \exists r. Y, \exists s. Y\}, S(Y) := \{\exists r. A\}$ use $>_S^+$

Y is minimal
$$\longrightarrow \sigma_S(Y) := \prod_{D \in S(Y)} D = \exists r.A$$

 $\underset{\text{for all } X >_{S}Y}{\overset{\sigma_{S}(Y) \text{ is defined}}{\longrightarrow} \sigma_{S}(X)} := \underset{D \in S(X)}{\sqcap} \sigma_{S}(D) = B \sqcap \exists r. \exists r. A \sqcap \exists s. \exists r. A \sqcup \exists s. \exists r. A \sqcap \exists s. \exists r. A \sqcap \exists s. \exists r. A \sqcup s. \exists r. A \sqcup s. \exists r. A \sqcup s. \exists s. \exists r. A \sqcup s. \exists r$

• A substitution is local if there exists an acyclic assignment S s.t. $\sigma = \sigma_S$.

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

Any acyclic assignment S induces a substitution σ_S:
 S(X) := {B, ∃r. Y, ∃s. Y}, S(Y) := {∃r.A} use >_S⁺

Y is minimal
$$\longrightarrow \sigma_{\mathcal{S}}(Y) := \prod_{D \in \mathcal{S}(Y)} D = \exists r.A$$

• A substitution is local if there exists an acyclic assignment S s.t. $\sigma = \sigma_S$.

 σ_{S} is a local unifier of $\Gamma := \{Y \sqsubseteq^{?} \exists r.A, X \sqsubseteq^{?} \exists r.Y \sqcap \exists s.Y, \exists s.X \sqsubseteq \exists s.B\}$

• An assignment S is called acyclic if $>_S^+$ is irreflexive

 $>_{S}^{+} = \{(X, Y)\}$ $>_{S}^{+} = \{(X, Y), (Y, X), (X, X), (Y, Y)\}$

Any acyclic assignment S induces a substitution σ_S:
 S(X) := {B, ∃r.Y, ∃s.Y}, S(Y) := {∃r.A} use >s⁺

$$Y \text{ is minimal} \longrightarrow \sigma_{S}(Y) := \prod_{D \in S(Y)} D = \exists r.A$$

• A substitution is local if there exists an acyclic assignment S s.t. $\sigma = \sigma_S$.

 σ_{S} is a local unifier of $\Gamma := \{Y \sqsubseteq^{?} \exists r.A, X \sqsubseteq^{?} \exists r.Y \sqcap \exists s.Y, \exists s.X \sqsubseteq \exists s.B\}$

Theorem 7 [BM10b, BBM12b]

Let Γ be a flat unification problem. If Γ has a unifier, then it also has a local unifier.

Proof of Theorem 7 (Sketch)

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

• Define the assignment S^{θ} as:

$$S^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

• Define the assignment S^{θ} as:

$$S^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

• Define the assignment S^{θ} as:

$$S^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

$$X_1 >_{S^{\theta}} X_2 >_{S^{\theta}} \ldots >_{S^{\theta}} X_n >_{S^{\theta}} X_1$$

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

• Define the assignment S^{θ} as:

$$S^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

$$X_1 >_{S^{\theta}} X_2 >_{S^{\theta}} \dots >_{S^{\theta}} X_n >_{S^{\theta}} X_1$$
$$\Rightarrow$$
$$\exists r_2.X_2 \in S^{\theta}(X_1), \exists r_3.X_3 \in S^{\theta}(X_2), \dots, \exists r_1.X_1 \in S^{\theta}(X_n)$$

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

• Define the assignment S^{θ} as:

$$\mathcal{S}^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

$$X_1 >_{S^{\theta}} X_2 >_{S^{\theta}} \dots >_{S^{\theta}} X_n >_{S^{\theta}} X_1$$

$$\Rightarrow$$

$$\exists r_2.X_2 \in S^{\theta}(X_1), \exists r_3.X_3 \in S^{\theta}(X_2), \dots, \exists r_1.X_1 \in S^{\theta}(X_n)$$

$$\Rightarrow$$

$$\theta(X_1) \sqsubseteq \exists r_2.\theta(X_2) \sqsubseteq \dots \sqsubseteq \exists r_1 \dots \exists r_n.\theta(X_1)$$

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

• Define the assignment S^{θ} as:

$$\mathcal{S}^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

• S^{θ} is acyclic. If not, we have:

$$X_1 >_{S^{\theta}} X_2 >_{S^{\theta}} \dots >_{S^{\theta}} X_n >_{S^{\theta}} X_1$$

$$\Rightarrow$$

$$\exists r_2.X_2 \in S^{\theta}(X_1), \exists r_3.X_3 \in S^{\theta}(X_2), \dots, \exists r_1.X_1 \in S^{\theta}(X_n)$$

$$\Rightarrow$$

$$\theta(X_1) \sqsubseteq \exists r_2.\theta(X_2) \sqsubseteq \dots \sqsubseteq \exists r_1 \dots \exists r_n.\theta(X_1)$$

Not true! Hence, $\sigma_{S^{\theta}}$ is a local substitution.

Proof of Theorem 7 (Sketch)

Let Γ be a flat unification problem that has a unifier θ .

• Define the assignment S^{θ} as:

$$S^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

• S^{θ} is acyclic. If not, we have:

$$X_1 >_{S^{\theta}} X_2 >_{S^{\theta}} \dots >_{S^{\theta}} X_n >_{S^{\theta}} X_1$$

$$\Rightarrow$$

$$\exists r_2.X_2 \in S^{\theta}(X_1), \exists r_3.X_3 \in S^{\theta}(X_2), \dots, \exists r_1.X_1 \in S^{\theta}(X_n)$$

$$\Rightarrow$$

$$\theta(X_1) \sqsubseteq \exists r_2.\theta(X_2) \sqsubseteq \dots \sqsubseteq \exists r_1 \dots \exists r_n.\theta(X_1)$$

Not true! Hence, $\sigma_{S^{\theta}}$ is a local substitution.

• It remains to show that $\sigma_{S^{\theta}}$ is a solution of Γ .

 $\sigma_{S^{\theta}}$ is a unifier of Γ

 $\sigma_{S^{\theta}}$ is a unifier of Γ

We prove a more general claim.

 $\sigma_{S^{\theta}}$ is a unifier of Γ

We prove a more general claim.

Let E_1, \ldots, E_m, D be atoms in Γ . Then, $\theta(E_1) \sqcap \ldots \sqcap \theta(E_m) \sqsubseteq \theta(D)$ \Rightarrow $\sigma_{S^{\theta}}(E_1) \sqcap \ldots \sqcap \sigma_{S^{\theta}}(E_m) \sqsubseteq \sigma_{S^{\theta}}(D).$

 $\sigma_{S^{\theta}}$ is a unifier of Γ

We prove a more general claim.

Lemma 8

Let E_1, \ldots, E_m, D be atoms in Γ . Then,

$$\theta(E_1) \sqcap \ldots \sqcap \theta(E_m) \sqsubseteq \theta(D)$$

$$\overrightarrow{\sigma}_{S^{\theta}}(E_1) \sqcap \ldots \sqcap \sigma_{S^{\theta}}(E_m) \sqsubseteq \sigma_{S^{\theta}}(D).$$

Proof technique. Use induction on:

$$\max\{\mathsf{rd}(\sigma_{S^{\theta}}(G)) \mid G \in \{E_1, \ldots, E_m, D\}\},\$$

together with the characterization of subsumption.

 $\sigma_{S^{\theta}}$ is a unifier of Γ

We prove a more general claim.

Lemma 8

Let E_1, \ldots, E_m, D be atoms in Γ . Then,

$$\theta(E_1) \sqcap \ldots \sqcap \theta(E_m) \sqsubseteq \theta(D)$$

$$\overline{\sigma}_{S^{\theta}}(E_1) \sqcap \ldots \sqcap \sigma_{S^{\theta}}(E_m) \sqsubseteq \sigma_{S^{\theta}}(D).$$

Proof technique. Use induction on:

$$\max\{\mathsf{rd}(\sigma_{S^{\theta}}(G)) \mid G \in \{E_1, \ldots, E_m, D\}\},\$$

together with the characterization of subsumption.

rd = role-depth of a concept description.

The decision problem. Upper bound (NP-algorithm)

Decision procedure

- 1 Guess an assignment S.
- **2** If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

The decision problem. Upper bound (NP-algorithm)

Decision procedure

- 1 Guess an assignment S.
- **2** If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

- 1 Guess an assignment S.
- **2** If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

The decision problem. Upper bound (NP-algorithm)

Decision procedure

- 1 Guess an assignment S.
- 2 If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

• S^{θ} is acyclic.

The decision problem. Upper bound (NP-algorithm)

- Decision procedure
 - 1 Guess an assignment S.
 - **2** If S is cyclic FAIL.
 - **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

- 1 Guess an assignment S.
- 2 If S is cyclic FAIL.
- **3** If σ_S solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

The procedure runs in non-deterministic polynomial time.

- 1 Guess an assignment S.
- **2** If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

The procedure runs in non-deterministic polynomial time.

• An acyclic assignment S can be guessed in polynomial time.

- 1 Guess an assignment S.
- 2 If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

The procedure runs in non-deterministic polynomial time.

- An acyclic assignment S can be guessed in polynomial time.
- How to check that σ_S is a unifier of Γ in polynomial time?

- 1 Guess an assignment S.
- **2** If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

The procedure runs in non-deterministic polynomial time.

- An acyclic assignment S can be guessed in polynomial time.
- How to check that σ_S is a unifier of Γ in polynomial time?

 σ_S can be of exponential size!

- 1 Guess an assignment S.
- 2 If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

The procedure runs in non-deterministic polynomial time.

- An acyclic assignment S can be guessed in polynomial time.
- How to check that σ_S is a unifier of Γ in polynomial time?

 $\begin{array}{c} \sigma_S \text{ can be of} \\ \text{exponential size!} \end{array} \xrightarrow{\text{solution}} \begin{array}{c} \text{acyclic TBox } \mathcal{T}_S \text{:} \\ X \doteq \prod_{D \in S(X)} D \end{array}$

- 1 Guess an assignment S.
- **2** If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

The procedure runs in non-deterministic polynomial time.

- An acyclic assignment S can be guessed in polynomial time.
- How to check that σ_S is a unifier of Γ in polynomial time?

 $\begin{array}{c} \sigma_{S} \text{ can be of} \\ \text{exponential size!} \end{array} \xrightarrow{\text{solution}} \begin{array}{c} \text{acyclic TBox } \mathcal{T}_{S} \colon \\ X \doteq \prod_{D \in S(X)} D \end{array} \xrightarrow{\sigma_{S}(C)} \subseteq \sigma_{S}(D) \text{ iff } C \sqsubseteq_{\mathcal{T}_{S}} D \end{array}$

- 1 Guess an assignment S.
- 2 If S is cyclic FAIL.
- **3** If σ_s solves Γ then SUCCESS.

Soundness. It is obvious.

Completeness. If Γ is unifiable, then it has a local unifier θ .

- S^{θ} is acyclic.
- It is easy to show that $\theta(X) \equiv \sigma_{S_{\theta}}(X)$.

The procedure runs in non-deterministic polynomial time.

- An acyclic assignment S can be guessed in polynomial time.
- How to check that σ_S is a unifier of Γ in polynomial time?

 $\begin{array}{c} \sigma_{S} \text{ can be of} \\ \text{exponential size!} \end{array} \xrightarrow{\text{solution}} \begin{array}{c} \text{acyclic TBox } \mathcal{T}_{S} \colon \\ X \doteq \prod_{D \in S(X)} D \end{array} \xrightarrow{\sigma_{S}(C)} \subseteq \sigma_{S}(D) \text{ iff } C \sqsubseteq_{\mathcal{T}_{S}} D \end{array}$

Subsumption w.r.t. \mathcal{T}_S can be checked in polynomial time.

Previous algorithm is a brutal "guess and then test".

• A direct implementation is very unlikely to perform well in practice.

- A direct implementation is very unlikely to perform well in practice.
- More practical algorithms are needed.

- A direct implementation is very unlikely to perform well in practice.
- More practical algorithms are needed.
 - Goal-oriented algorithm [BM10b].

- A direct implementation is very unlikely to perform well in practice.
- More practical algorithms are needed.
 - Goal-oriented algorithm [BM10b].
 - SAT Encoding.

More practical algorithms - SAT Encoding [BM10a]

More practical algorithms - SAT Encoding [BM10a]

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

• the size of φ_Γ is polynomial in the size of $\Gamma,$ and

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem $\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem
$\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$

prop. variab	es	
$[A \not\sqsubseteq B]$	\rightarrow	$\sigma(A) \not\sqsubseteq \sigma(B)$
[X > Y]	\rightarrow	prevents $\neg [X \not\sqsubseteq \exists r.X]$

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem $\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$ $[A \not\sqsubseteq B] \rightarrow \sigma(A) \not\sqsubseteq \sigma(B)$ $[X > Y] \rightarrow \text{ prevents } \neg[X \not\sqsubseteq \exists r.X]$

 $\label{eq:Gamma-formula} \ensuremath{\,\,\Gamma} \ \text{has a solution:} \ [C_1 \not\sqsubseteq D] \land \ldots \land [C_n \not\sqsubseteq D] \rightarrow \\$

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem $\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$ $[A \not\sqsubseteq B] \rightarrow \sigma(A) \not\sqsubseteq \sigma(B)$ $[X > Y] \rightarrow \text{ prevents } \neg[X \not\sqsubseteq \exists r.X]$

 $\[\]$ has a solution: $[C_1 \not\sqsubseteq D] \land \ldots \land [C_n \not\sqsubseteq D] \rightarrow$ Subsumption properties in $\mathcal{EL}: \rightarrow [A \not\sqsubseteq B], \rightarrow [\exists r.A \not\sqsubseteq \exists s.B]$, transitivity, ...

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem $\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$ $[A \not\sqsubseteq B] \rightarrow \sigma(A) \not\sqsubseteq \sigma(B)$ $[X > Y] \rightarrow \text{ prevents } \neg[X \not\sqsubseteq \exists r.X]$

 $\begin{array}{l} \mbox{$\Gamma$ has a solution: $[C_1 \not\sqsubseteq D] \land \ldots \land [C_n \not\sqsubseteq D] \rightarrow} \\ \mbox{Subsumption properties in \mathcal{EL}: $\rightarrow $[A \not\sqsubseteq B]$, $\rightarrow $[\exists r.A \not\sqsubseteq \exists s.B]$, transitivity, \dots } \\ \mbox{Properties of $>: $[X > X] \rightarrow, $\rightarrow $[X > Y] \lor $[X \not\sqsubseteq \exists r.Y]$, transitivity} } \end{array}$

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem $\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$ $[A \not\sqsubseteq B] \rightarrow \sigma(A) \not\sqsubseteq \sigma(B)$ $[X > Y] \rightarrow \text{ prevents } \neg[X \not\sqsubseteq \exists r.X]$

Advantages

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem $\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$ $[A \not\sqsubseteq B] \rightarrow \sigma(A) \not\sqsubseteq \sigma(B)$ $[X > Y] \rightarrow \text{ prevents } \neg[X \not\sqsubseteq \exists r.X]$

Advantages

• a new in NP proof (maybe much simpler).

Given a flat \mathcal{EL} -unification problem Γ , construct a propositional formula φ_{Γ} s.t.:

- the size of φ_{Γ} is polynomial in the size of Γ , and
- Γ has a unifier **if**, and only **if**, φ_{Γ} is satisfiable.

Idea.

unif. problem $\Gamma = \{C_1 \sqcap \ldots \sqcap C_n \sqsubseteq^? D\}$ $[A \not\sqsubseteq B] \rightarrow \sigma(A) \not\sqsubseteq \sigma(B)$ $[X > Y] \rightarrow \text{ prevents } \neg[X \not\sqsubseteq \exists r.X]$

 $\begin{array}{l} \mbox{$\Gamma$ has a solution: $[C_1 \not\sqsubseteq D] \land \ldots \land [C_n \not\sqsubseteq D] \rightarrow} \\ \mbox{Subsumption properties in \mathcal{EL}: $\rightarrow $[A \not\sqsubseteq B]$, $\rightarrow $[\exists r.A \not\sqsubseteq \exists s.B]$, transitivity, \dots} \\ \mbox{Properties of $>: $[X > X] \rightarrow, $\rightarrow $[X > Y] \lor $[X \not\sqsubseteq \exists r.Y]$, transitivity} \end{array}$

Advantages

- a new in NP proof (maybe much simpler).
- allows to employ highly optimized SAT solvers to implement an $\mathcal{EL}\text{-unification}$ algorithm.

All the existent algorithms have in common:

All the existent algorithms have in common:

• they compute all minimal unifiers (this is not \leq):

All the existent algorithms have in common:

• they compute all minimal unifiers (this is not \leq):

Let \mathcal{X} be a set of variables, we define $\sigma \geq_{\mathcal{X}} \theta$ iff $\sigma(X) \sqsubseteq \theta(X)$ holds for all $X \in \mathcal{X}$. A unifier σ is \mathcal{X} -minimal if no other unifier is strictly smaller.

All the existent algorithms have in common:

• they compute all minimal unifiers (this is not \leq):

Let \mathcal{X} be a set of variables, we define $\sigma \geq_{\mathcal{X}} \theta$ iff $\sigma(X) \sqsubseteq \theta(X)$ holds for all $X \in \mathcal{X}$. A unifier σ is \mathcal{X} -minimal if no other unifier is strictly smaller.

• they also compute local unifiers that are not minimal.

All the existent algorithms have in common:

• they compute all minimal unifiers (this is not \leq):

Let \mathcal{X} be a set of variables, we define $\sigma \geq_{\mathcal{X}} \theta$ iff $\sigma(X) \sqsubseteq \theta(X)$ holds for all $X \in \mathcal{X}$. A unifier σ is \mathcal{X} -minimal if no other unifier is strictly smaller.

- they also compute local unifiers that are not minimal.
- very small unification problems can have hundreds of local unifiers.

All the existent algorithms have in common:

• they compute all minimal unifiers (this is not \leq):

Let \mathcal{X} be a set of variables, we define $\sigma \geq_{\mathcal{X}} \theta$ iff $\sigma(X) \sqsubseteq \theta(X)$ holds for all $X \in \mathcal{X}$. A unifier σ is \mathcal{X} -minimal if no other unifier is strictly smaller.

- they also compute local unifiers that are not minimal.
- very small unification problems can have hundreds of local unifiers.

Minimal unifiers represent a significantly smaller (in many cases) subset of the set of local unifiers.

All the existent algorithms have in common:

• they compute all minimal unifiers (this is not \leq):

Let \mathcal{X} be a set of variables, we define $\sigma \geq_{\mathcal{X}} \theta$ iff $\sigma(X) \sqsubseteq \theta(X)$ holds for all $X \in \mathcal{X}$. A unifier σ is \mathcal{X} -minimal if no other unifier is strictly smaller.

- they also compute local unifiers that are not minimal.
- very small unification problems can have hundreds of local unifiers.

Minimal unifiers represent a significantly smaller (in many cases) subset of the set of local unifiers.

Is it possible to have an NP-algorithm that computes only (and all) \mathcal{X} -minimal unifiers?

All the existent algorithms have in common:

• they compute all minimal unifiers (this is not \leq):

Let \mathcal{X} be a set of variables, we define $\sigma \geq_{\mathcal{X}} \theta$ iff $\sigma(X) \sqsubseteq \theta(X)$ holds for all $X \in \mathcal{X}$. A unifier σ is \mathcal{X} -minimal if no other unifier is strictly smaller.

- they also compute local unifiers that are not minimal.
- very small unification problems can have hundreds of local unifiers.

Minimal unifiers represent a significantly smaller (in many cases) subset of the set of local unifiers.

Is it possible to have an NP-algorithm that computes only (and all) \mathcal{X} -minimal unifiers?

• Answer: seems unlikely!

The minimal unifier containment problem:

Instance:	A flat $\mathcal{EL}\text{-unification}$ problem $\Gamma,$ a set $\mathcal{X}\subseteq N_v,$ a concept constant
	$A \in N_{C}$ and a concept variable $X \in \mathcal{X}$.
Question:	Is there an \mathcal{X} -minimal unifier σ of Γ s.t. $\sigma(X) \sqsubset A$?

The minimal unifier containment problem:

Instance:	A flat \mathcal{EL} -unification problem Γ , a set $\mathcal{X} \subseteq N_v$, a concept constant
	$A \in N_{C}$ and a concept variable $X \in \mathcal{X}$.
Question:	Is there an \mathcal{X} -minimal unifier σ of Γ s.t. $\sigma(X) \sqsubset A$?

This problem is Σ_2^p -complete (Th. 4.1 [BBM12a]).

The minimal unifier containment problem:

Instance:	A flat \mathcal{EL} -unification problem Γ , a set $\mathcal{X} \subseteq N_v$, a concept constant
	$A \in N_{C}$ and a concept variable $X \in \mathcal{X}$.
Question:	Is there an \mathcal{X} -minimal unifier σ of Γ s.t. $\sigma(X) \sqsubseteq A$?

This problem is Σ_2^p -complete (Th. 4.1 [BBM12a]).

Assume there is an NP-algorithm $\mathcal A$ that computes exactly the set of $\mathcal X$ -minimal unifiers:

The minimal unifier containment problem:

Instance:	A flat \mathcal{EL} -unification problem Γ , a set $\mathcal{X} \subseteq N_v$, a concept constant
	$A \in N_{C}$ and a concept variable $X \in \mathcal{X}$.
Question:	Is there an \mathcal{X} -minimal unifier σ of Γ s.t. $\sigma(X) \sqsubseteq A$?

This problem is Σ_2^p -complete (Th. 4.1 [BBM12a]).

Assume there is an NP-algorithm $\mathcal A$ that computes exactly the set of $\mathcal X$ -minimal unifiers:

• Extend A with checking, for successful paths, whether $\sigma(X) \sqsubseteq A$.

The minimal unifier containment problem:

Instance:	A flat \mathcal{EL} -unification problem Γ , a set $\mathcal{X} \subseteq N_v$, a concept constant
	$A \in N_{C}$ and a concept variable $X \in \mathcal{X}$.
Question:	Is there an \mathcal{X} -minimal unifier σ of Γ s.t. $\sigma(X) \sqsubseteq A$?

This problem is Σ_2^p -complete (Th. 4.1 [BBM12a]).

Assume there is an NP-algorithm $\mathcal A$ that computes exactly the set of $\mathcal X$ -minimal unifiers:

- Extend A with checking, for successful paths, whether $\sigma(X) \sqsubseteq A$.
- The minimal unifier containment problem would be decidable in NP.

The minimal unifier containment problem:

Instance:	A flat \mathcal{EL} -unification problem Γ , a set $\mathcal{X} \subseteq N_v$, a concept constant
	$A \in N_{C}$ and a concept variable $X \in \mathcal{X}$.
Question:	Is there an \mathcal{X} -minimal unifier σ of Γ s.t. $\sigma(X) \sqsubseteq A$?

This problem is Σ_2^p -complete (Th. 4.1 [BBM12a]).

Assume there is an NP-algorithm $\mathcal A$ that computes exactly the set of $\mathcal X$ -minimal unifiers:

- Extend A with checking, for successful paths, whether $\sigma(X) \sqsubseteq A$.
- The minimal unifier containment problem would be decidable in NP.
- NP= $\Sigma_2^p \Rightarrow$ the polynomial hierarchy collapses.

Unification Modulo \mathcal{EL} -TBoxes

• The presence of a non-empty TBoxes adds new information

• The presence of a non-empty TBoxes adds new information

 $\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r.X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r.A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r.A, \dots$$

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r.X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r.A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r.A, \dots$$

• The previous notion of locality does not work.

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

 $\mathcal{T} = \{B \sqsubseteq \exists s.D, D \sqsubseteq B\}$

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

A unifier $\theta = \{Y_1 \mapsto A_1 \sqcap B, Y_2 \mapsto A_2 \sqcap B, X \mapsto \exists s.B\}$

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

A unifier $\theta = \{Y_1 \mapsto A_1 \sqcap B, Y_2 \mapsto A_2 \sqcap B, X \mapsto \exists s.B\}$

The construction of $\sigma_{S^{\theta}}$ w.r.t. $\sqsubseteq_{\mathcal{T}}$ yields a cyclic assignment.

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

A unifier $\theta = \{Y_1 \mapsto A_1 \sqcap B, Y_2 \mapsto A_2 \sqcap B, X \mapsto \exists s.B\}$

The construction of $\sigma_{S^{\theta}}$ w.r.t. $\sqsubseteq_{\mathcal{T}}$ yields a cyclic assignment.

$$\theta(X) = \exists s.B \sqsubseteq_{\mathcal{T}} \exists s.\exists s.B = \theta(\exists s.X) \quad \Rightarrow \quad \exists s.X \in S^{\theta}(X)$$

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

A unifier $\theta = \{Y_1 \mapsto A_1 \sqcap B, Y_2 \mapsto A_2 \sqcap B, X \mapsto \exists s.B\}$

The construction of $\sigma_{S^{\theta}}$ w.r.t. $\sqsubseteq_{\mathcal{T}}$ yields a cyclic assignment.

$$\theta(X) = \exists s.B \sqsubseteq_{\mathcal{T}} \exists s.\exists s.B = \theta(\exists s.X) \quad \Rightarrow \quad \exists s.X \in S^{\theta}(X)$$

One can show that Γ does not have local unifiers!

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

A unifier $\theta = \{Y_1 \mapsto A_1 \sqcap B, Y_2 \mapsto A_2 \sqcap B, X \mapsto \exists s.B\}$

The construction of $\sigma_{S^{\theta}}$ w.r.t. $\sqsubseteq_{\mathcal{T}}$ yields a cyclic assignment.

$$\theta(X) = \exists s.B \sqsubseteq_{\mathcal{T}} \exists s.\exists s.B = \theta(\exists s.X) \quad \Rightarrow \quad \exists s.X \in S^{\theta}(X)$$

One can show that Γ does not have local unifiers!

• Decidability of *EL*-unification w.r.t. general TBoxes remains an open problem.

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

A unifier $\theta = \{Y_1 \mapsto A_1 \sqcap B, Y_2 \mapsto A_2 \sqcap B, X \mapsto \exists s.B\}$

The construction of $\sigma_{S^{\theta}}$ w.r.t. $\sqsubseteq_{\mathcal{T}}$ yields a cyclic assignment.

$$\theta(X) = \exists s.B \sqsubseteq_{\mathcal{T}} \exists s.\exists s.B = \theta(\exists s.X) \quad \Rightarrow \quad \exists s.X \in S^{\theta}(X)$$

One can show that Γ does not have local unifiers!

- Decidability of *EL*-unification w.r.t. general TBoxes remains an open problem.
- What can we do?

• The presence of a non-empty TBoxes adds new information

$$\Gamma = \{X \sqsubseteq^? \exists r. X\} \text{ has solutions w.r.t. } \mathcal{T} = \{A \sqsubseteq \exists r. A\}$$
$$\downarrow$$
$$\sigma(X) = A, \sigma(X) = \exists r. A, \dots$$

• The previous notion of locality does not work.

$$\mathcal{T} = \{ B \sqsubseteq \exists s.D, D \sqsubseteq B \} \qquad \Gamma = \{ A_1 \sqcap B \equiv^? Y_1, A_2 \sqcap B \equiv^? Y_2, \exists s.Y_1 \sqsubseteq^? X \\ \exists s.Y_2 \sqsubseteq^? X, X \sqsubseteq^? \exists s.X \}$$

A unifier $\theta = \{Y_1 \mapsto A_1 \sqcap B, Y_2 \mapsto A_2 \sqcap B, X \mapsto \exists s.B\}$

The construction of $\sigma_{S^{\theta}}$ w.r.t. $\sqsubseteq_{\mathcal{T}}$ yields a cyclic assignment.

$$\theta(X) = \exists s.B \sqsubseteq_{\mathcal{T}} \exists s.\exists s.B = \theta(\exists s.X) \quad \Rightarrow \quad \exists s.X \in S^{\theta}(X)$$

One can show that Γ does not have local unifiers!

- Decidability of *EL*-unification w.r.t. general TBoxes remains an open problem.
- What can we do? Consider a restricted class of TBoxes.

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted iff there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C.$

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted iff there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C$.

Some remarks:

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted iff there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C$.

Some remarks:

• cycles $\exists w. C \sqsubseteq_T C$ are allowed.

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted **iff** there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C.$

Some remarks:

- cycles $\exists w. C \sqsubseteq_T C$ are allowed.
- cycle-restrictedness can be checked in polynomial time.

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted **iff** there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C.$

Some remarks:

- cycles $\exists w. C \sqsubseteq_T C$ are allowed.
- cycle-restrictedness can be checked in polynomial time.

Locality is regained under cycle-restrictedness

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted **iff** there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C.$

Some remarks:

- cycles $\exists w. C \sqsubseteq_T C$ are allowed.
- cycle-restrictedness can be checked in polynomial time.

Locality is regained under cycle-restrictedness

• Define the assignment S^{θ} as:

$$S^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq_{\mathcal{T}} heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}} \}$$

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted **iff** there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C.$

Some remarks:

- cycles $\exists w. C \sqsubseteq_T C$ are allowed.
- cycle-restrictedness can be checked in polynomial time.

Locality is regained under cycle-restrictedness

• Define the assignment S^{θ} as:

$${\mathcal S}^{ heta}(X):=\{D\in \operatorname{At}_{\mathsf{nv}}\mid heta(X)\sqsubseteq_{\mathcal T} heta(D)\}, ext{ for all } X\in \mathsf{N}_{\mathsf{v}}\}$$

• S^{θ} must be acyclic, for otherwise:

$$\theta(X_1) \sqsubseteq_{\mathcal{T}} \exists r_2.\theta(X_2) \sqsubseteq_{\mathcal{T}} \ldots \sqsubseteq_{\mathcal{T}} \exists r_1 \ldots \exists r_n.\theta(X_1)$$

Cycle-restricted TBoxes

A general TBox \mathcal{T} is called cycle-restricted **iff** there is no word $w \in N_R^+$ and \mathcal{EL} concept C such that $C \sqsubseteq_{\mathcal{T}} \exists w.C.$

Some remarks:

- cycles $\exists w. C \sqsubseteq_T C$ are allowed.
- cycle-restrictedness can be checked in polynomial time.

Locality is regained under cycle-restrictedness

• Define the assignment S^{θ} as:

$$S^{ heta}(X) := \{ D \in \mathsf{At}_{\mathsf{nv}} \mid heta(X) \sqsubseteq_{\mathcal{T}} heta(D) \}, ext{ for all } X \in \mathsf{N}_{\mathsf{v}}.$$

• S^{θ} must be acyclic, for otherwise:

$$\theta(X_1) \sqsubseteq_{\mathcal{T}} \exists r_2.\theta(X_2) \sqsubseteq_{\mathcal{T}} \ldots \sqsubseteq_{\mathcal{T}} \exists r_1 \ldots \exists r_n.\theta(X_1)$$

• $\sigma_{S^{\theta}}$ is a local substitution.

Theorem 9 [BBM12b]

Let \mathcal{T} be a flat cycle-restricted TBox and Γ a flat unification problem. If Γ has a unifier w.r.t. \mathcal{T} , then it also has a local unifier w.r.t. \mathcal{T} .

Theorem 9 [BBM12b]

Let \mathcal{T} be a flat cycle-restricted TBox and Γ a flat unification problem. If Γ has a unifier w.r.t. \mathcal{T} , then it also has a local unifier w.r.t. \mathcal{T} .

The proof is similar as for $\mathcal{T} = \emptyset$, i.e., we proof the corresponding more general claim:

Theorem 9 [BBM12b]

Let \mathcal{T} be a flat cycle-restricted TBox and Γ a flat unification problem. If Γ has a unifier w.r.t. \mathcal{T} , then it also has a local unifier w.r.t. \mathcal{T} .

The proof is similar as for $\mathcal{T} = \emptyset$, i.e., we proof the corresponding more general claim:

Lemma 10 Let E_1, \ldots, E_m, D be atoms in Γ . Then, $\theta(E_1) \sqcap \ldots \sqcap \theta(E_m) \sqsubseteq_{\mathcal{T}} \theta(D)$ \Rightarrow $\sigma_{S^{\theta}}(E_1) \sqcap \ldots \sqcap \sigma_{S^{\theta}}(E_m) \sqsubseteq_{\mathcal{T}} \sigma_{S^{\theta}}(D).$

Theorem 9 [BBM12b]

Let \mathcal{T} be a flat cycle-restricted TBox and Γ a flat unification problem. If Γ has a unifier w.r.t. \mathcal{T} , then it also has a local unifier w.r.t. \mathcal{T} .

The proof is similar as for $\mathcal{T} = \emptyset$, i.e., we proof the corresponding more general claim:

Lemma 10 Let E_1, \ldots, E_m, D be atoms in Γ . Then, $\theta(E_1) \sqcap \ldots \sqcap \theta(E_m) \sqsubseteq_{\mathcal{T}} \theta(D)$ \Rightarrow $\sigma_{S^{\theta}}(E_1) \sqcap \ldots \sqcap \sigma_{S^{\theta}}(E_m) \sqsubseteq_{\mathcal{T}} \sigma_{S^{\theta}}(D).$ To take into account \mathcal{T} :

Theorem 9 [BBM12b]

Let \mathcal{T} be a flat cycle-restricted TBox and Γ a flat unification problem. If Γ has a unifier w.r.t. \mathcal{T} , then it also has a local unifier w.r.t. \mathcal{T} .

The proof is similar as for $\mathcal{T} = \emptyset$, i.e., we proof the corresponding more general claim:

Lemma 10 Let E_1, \ldots, E_m, D be atoms in Γ . Then, $\theta(E_1) \sqcap \ldots \sqcap \theta(E_m) \sqsubseteq_{\mathcal{T}} \theta(D)$ \Rightarrow $\sigma_{S^{\theta}}(E_1) \sqcap \ldots \sqcap \sigma_{S^{\theta}}(E_m) \sqsubseteq_{\mathcal{T}} \sigma_{S^{\theta}}(D).$ To take into account \mathcal{T} :

• A new characterization of subsumption is developed.

Theorem 9 [BBM12b]

Let \mathcal{T} be a flat cycle-restricted TBox and Γ a flat unification problem. If Γ has a unifier w.r.t. \mathcal{T} , then it also has a local unifier w.r.t. \mathcal{T} .

The proof is similar as for $\mathcal{T} = \emptyset$, i.e., we proof the corresponding more general claim:

Lemma 10 Let E_1, \ldots, E_m, D be atoms in Γ . Then, $\theta(E_1) \sqcap \ldots \sqcap \theta(E_m) \sqsubseteq_{\mathcal{T}} \theta(D)$ \Rightarrow $\sigma_{S^{\theta}}(E_1) \sqcap \ldots \sqcap \sigma_{S^{\theta}}(E_m) \sqsubseteq_{\mathcal{T}} \sigma_{S^{\theta}}(D).$ To take into account \mathcal{T} :

- A new characterization of subsumption is developed.
- A slightly modified induction hypothesis is used.

Investigated in detail for the case where $\mathcal{T}=\emptyset$

Investigated in detail for the case where $\mathcal{T} = \emptyset$

• The problem is NP-complete. NP-hardness holds even for the special case of matching.

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].
- Computing minimal *EL*-unifiers is hard.

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].
- Computing minimal *EL*-unifiers is hard.

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].
- Computing minimal *EL*-unifiers is hard.

Unification modulo an arbitrary TBox

• Decidability is an open problem.

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].
- Computing minimal *EL*-unifiers is hard.

- Decidability is an open problem.
- Positive results exist only if the TBox or the unification problem are restricted:

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].
- Computing minimal *EL*-unifiers is hard.

- Decidability is an open problem.
- Positive results exist only if the TBox or the unification problem are restricted:
 - Matching w.r.t. a general TBox is NP-complete [BM14].

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].
- Computing minimal *EL*-unifiers is hard.

- Decidability is an open problem.
- Positive results exist only if the TBox or the unification problem are restricted:
 - Matching w.r.t. a general TBox is NP-complete [BM14].
 - Unification w.r.t. cycle-restricted TBoxes is NP-complete.

Investigated in detail for the case where $\mathcal{T} = \emptyset$

- The problem is NP-complete. NP-hardness holds even for the special case of matching.
- Development of practical algorithms: goal oriented algorithm and SAT encoding.
- Unification Solver UEL: based on the SAT encoding [BMM12].
- Computing minimal *EL*-unifiers is hard.

- Decidability is an open problem.
- Positive results exist only if the TBox or the unification problem are restricted:
 - Matching w.r.t. a general TBox is NP-complete [BM14].
 - Unification w.r.t. cycle-restricted TBoxes is NP-complete.
 - Goal oriented algorithm and SAT encoding.

References I

Franz Baader, Sebastian Brandt, and Carsten Lutz. Pushing the *EL* envelope.

In Leslie Pack Kaelbling and Alessandro Saffiotti, editors, *Proc. of the 19th Int. Joint Conf. on Artificial Intelligence (IJCAI 2005)*, pages 364–369, Edinburgh (UK), 2005. Morgan Kaufmann, Los Altos.

Franz Baader, Stefan Borgwardt, and Barbara Morawska.

Computing minimal el-unifiers is hard.

In Advances in Modal Logic 9, papers from the ninth conference on "Advances in Modal Logic," held in Copenhagen, Denmark, 22-25 August 2012, pages 18–35. College Publications, 2012.

Franz Baader, Stefan Borgwardt, and Barbara Morawska.
 Extending unification in *EL* towards general TBoxes.
 In Proc. of the 13th Int. Conf. on Principles of Knowledge Representation and Reasoning (KR 2012), pages 568–572. AAAI Press/The MIT Press, 2012.

Franz Baader and Ralf Küsters.

Matching in description logics with existential restrictions. In Proc. of the 7th Int. Conf. on Principles of Knowledge Representation and Reasoning (KR 2000), pages 261–272, 2000.

References II

Franz Baader and Barbara Morawska.

SAT encoding of unification in EL.

In Logic for Programming, Artificial Intelligence, and Reasoning - 17th International Conference, LPAR-17, Yogyakarta, Indonesia, October 10-15, 2010. Proceedings, volume 6397 of Lecture Notes in Computer Science, pages 97–111. Springer, 2010.

Franz Baader and Barbara Morawska. Unification in the description logic \mathcal{EL} . Logical Methods in Computer Science, 6(3), 2010.

Franz Baader and Barbara Morawska.

Matching with respect to general concept inclusions in the description logic *EL*. In *KI 2014: Advances in Artificial Intelligence - 37th Annual German Conference on AI, Stuttgart, Germany, September 22-26, 2014. Proceedings*, volume 8736 of *Lecture Notes in Computer Science*, pages 135–146. Springer, 2014.

References III

Franz Baader, Julian Mendez, and Barbara Morawska.

UEL: unification solver for the description logic $\Delta \{EL\}\$ - system description.

In Automated Reasoning - 6th International Joint Conference, IJCAR 2012, Manchester, UK, June 26-29, 2012. Proceedings, volume 7364 of Lecture Notes in Computer Science, pages 45–51. Springer, 2012.



Ralf Küsters.

Non-Standard Inferences in Description Logics, volume 2100 of Lecture Notes in Computer Science.

Springer, 2001.