

Unification in Description Logics

Part IV: Related work in Modal Logics

Oliver Fernández Gil

Chair of Automata Theory



ESLLI'19

Riga, August 2019

Basic modal systems

Basic modal systems

Let x_1, x_2, \dots be propositional variables and p_1, \dots, p_m modal parameters.

Basic modal systems

Let x_1, x_2, \dots be propositional variables and p_1, \dots, p_m modal parameters.

Basic modal propositional formulas

$$A, B ::= x \mid \top \mid \neg A \mid A \wedge B \mid \Box_p A,$$

where x is a propositional variable and p a modal parameter.

Basic modal systems

Let x_1, x_2, \dots be propositional variables and p_1, \dots, p_m modal parameters.

Basic modal propositional formulas

$$A, B ::= x \mid \top \mid \neg A \mid A \wedge B \mid \Box_p A,$$

where x is a propositional variable and p a modal parameter.

Axiom system L

A set of formulas closed under substitutions such that it contains:

Basic modal systems

Let x_1, x_2, \dots be propositional variables and p_1, \dots, p_m modal parameters.

Basic modal propositional formulas

$$A, B ::= x \mid \top \mid \neg A \mid A \wedge B \mid \Box_p A,$$

where x is a propositional variable and p a modal parameter.

Axiom system L

A set of formulas closed under substitutions such that it contains:

- all classical tautologies (e.g. $\neg(x \wedge \neg x)$).

Basic modal systems

Let x_1, x_2, \dots be propositional variables and p_1, \dots, p_m modal parameters.

Basic modal propositional formulas

$$A, B ::= x \mid \top \mid \neg A \mid A \wedge B \mid \Box_p A,$$

where x is a propositional variable and p a modal parameter.

Axiom system L

A set of formulas closed under substitutions such that it contains:

- all classical tautologies (e.g. $\neg(x \wedge \neg x)$).
- the Aristotle axiom $\Box(x \rightarrow y) \rightarrow (\Box x \rightarrow \Box y)$.

Modal Logic (ML)

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or
- it can be obtained from previous elements in the sequence by applying the rules:

$$\frac{x, x \rightarrow y}{y} (\text{MP}) \quad \text{or} \quad \frac{x}{\Box x} (\text{necessitation}).$$

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or
- it can be obtained from previous elements in the sequence by applying the rules:

$$\frac{x, x \rightarrow y}{y} (\text{MP}) \quad \text{or} \quad \frac{x}{\Box x} (\text{necessitation}).$$

Modal Logic L

The set of formulas which are derivable from the axiom system L .

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or
- it can be obtained from previous elements in the sequence by applying the rules:

$$\frac{x, x \rightarrow y}{y} (\text{MP}) \quad \text{or} \quad \frac{x}{\Box x} (\text{necessitation}).$$

Modal Logic L

The set of formulas which are derivable from the axiom system L .

Examples of modal logics

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or
- it can be obtained from previous elements in the sequence by applying the rules:

$$\frac{x, x \rightarrow y}{y} (\text{MP}) \quad \text{or} \quad \frac{x}{\Box x} (\text{necessitation}).$$

Modal Logic L

The set of formulas which are derivable from the axiom system L .

Examples of modal logics

- The minimum modal logic called K (with only one modal parameter).

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or
- it can be obtained from previous elements in the sequence by applying the rules:

$$\frac{x, x \rightarrow y}{y} (\text{MP}) \quad \text{or} \quad \frac{x}{\Box x} (\text{necessitation}).$$

Modal Logic L

The set of formulas which are derivable from the axiom system L .

Examples of modal logics

- The minimum modal logic called K (with only one modal parameter).
- The logic K4: includes the axiom $\Box x \rightarrow \Box \Box x$.

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or
- it can be obtained from previous elements in the sequence by applying the rules:

$$\frac{x, x \rightarrow y}{y} \text{ (MP)} \quad \text{or} \quad \frac{x}{\Box x} \text{ (necessitation).}$$

Modal Logic L

The set of formulas which are derivable from the axiom system L .

Examples of modal logics

- The minimum modal logic called K (with only one modal parameter).
- The logic K4: includes the axiom $\Box x \rightarrow \Box \Box x$.
- The logic S4: consists of K4 plus the axiom $\Box x \rightarrow x$.

Modal Logic (ML)

Derivable formulas in L

A formula A is derivable in L ($\vdash_L A$) iff there is a seq. of formulas $B_1, \dots, B_n = A$ s.t.:

- $B_i \in L$, or
- it can be obtained from previous elements in the sequence by applying the rules:

$$\frac{x, x \rightarrow y}{y} (\text{MP}) \quad \text{or} \quad \frac{x}{\Box x} (\text{necessitation}).$$

Modal Logic L

The set of formulas which are derivable from the axiom system L .

Examples of modal logics

- The minimum modal logic called K (with only one modal parameter).
- The logic K4: includes the axiom $\Box x \rightarrow \Box \Box x$.
- The logic S4: consists of K4 plus the axiom $\Box x \rightarrow x$.
- ...

Modal Logic. Semantics

Modal Logic. Semantics

Kripke structures

Modal Logic. Semantics

Kripke structures

- Kripke frame. A pair $F = (W, (R_{p_1}, \dots, R_{p_n}))$ where:
 - W is a non-empty set of states (or possible worlds).
 - $(R_{p_1}, \dots, R_{p_n})$ is a tuple of binary relations over W (accessibility relations).

Modal Logic. Semantics

Kripke structures

- Kripke frame. A pair $F = (W, (R_{p_1}, \dots, R_{p_n}))$ where:
 - W is a non-empty set of states (or possible worlds).
 - $(R_{p_1}, \dots, R_{p_n})$ is a tuple of binary relations over W (accessibility relations).

- Kripke model. A pair $M = (F, V)$ where V is a valuation of the propositional variables:

$$V : Vars \rightarrow 2^W.$$

Modal Logic. Semantics

Validity

Modal Logic. Semantics

Validity

- A is valid in a world w of a model M ($M, w \models A$) iff

$$M, w \models \top$$

$$M, w \models \neg A \text{ iff } M, w \not\models A$$

$$M, w \models A \wedge B \text{ iff } M, w \models A \text{ and } M, w \models B$$

$$M, w \models \Box_p A \text{ iff for all } w' : R_p(w, w') \implies M, w' \models A.$$

Modal Logic. Semantics

Validity

- A is valid in a world w of a model M ($M, w \models A$) iff

$$M, w \models \top$$

$$M, w \models \neg A \text{ iff } M, w \not\models A$$

$$M, w \models A \wedge B \text{ iff } M, w \models A \text{ and } M, w \models B$$

$$M, w \models \Box_p A \text{ iff for all } w' : R_p(w, w') \implies M, w' \models B.$$

- A is valid in a model M ($M \models A$) iff it is valid in all its worlds.

Modal Logic. Semantics

Validity

- A is valid in a world w of a model M ($M, w \models A$) iff

$$M, w \models \top$$

$$M, w \models \neg A \text{ iff } M, w \not\models A$$

$$M, w \models A \wedge B \text{ iff } M, w \models A \text{ and } M, w \models B$$

$$M, w \models \Box_p A \text{ iff for all } w' : R_p(w, w') \implies M, w' \models B.$$

- A is valid in a model M ($M \models A$) iff it is valid in all its worlds.
- A is valid in a frame F ($F \models A$) iff it is valid in all the models based on F .

Modal Logic. Semantics

Validity

- A is valid in a world w of a model M ($M, w \models A$) iff

$$M, w \models \top$$

$$M, w \models \neg A \text{ iff } M, w \not\models A$$

$$M, w \models A \wedge B \text{ iff } M, w \models A \text{ and } M, w \models B$$

$$M, w \models \Box_p A \text{ iff for all } w' : R_p(w, w') \implies M, w' \models B.$$

- A is valid in a model M ($M \models A$) iff it is valid in all its worlds.
- A is valid in a frame F ($F \models A$) iff it is valid in all the models based on F .
- A is valid in a class of Kripke frames K ($K \models A$) iff it is valid in all $F \in K$.

Modal Logic. Semantics

Validity

- A is valid in a world w of a model M ($M, w \models A$) iff

$$M, w \models \top$$

$$M, w \models \neg A \text{ iff } M, w \not\models A$$

$$M, w \models A \wedge B \text{ iff } M, w \models A \text{ and } M, w \models B$$

$$M, w \models \Box_p A \text{ iff for all } w' : R_p(w, w') \implies M, w' \models B.$$

- A is valid in a model M ($M \models A$) iff it is valid in all its worlds.
- A is valid in a frame F ($F \models A$) iff it is valid in all the models based on F .
- A is valid in a class of Kripke frames K ($K \models A$) iff it is valid in all $F \in K$.
- $L(K)$ is called the modal logic induced by the class of frames K .

Derivability vs Semantics (or \vdash_L vs. validity)

Derivability vs Semantics (or \vdash_L vs. validity)

In many cases \vdash_L corresponds to validity in a class of frames K .

- Minimum modal logic K:

$\vdash_K A$ iff $K \models A$ (K is the class of all frames).

Derivability vs Semantics (or \vdash_L vs. validity)

In many cases \vdash_L corresponds to validity in a class of frames K .

- Minimum modal logic K:

$$\vdash_K A \text{ iff } K \models A \quad (K \text{ is the class of all frames}).$$

- Modal logic K4 ($\Box x \rightarrow \Box \Box x$)

$$\vdash_{K4} A \text{ iff } T \models A \quad (T \text{ is the class of all transitive frames.})$$

Derivability vs Semantics (or \vdash_L vs. validity)

In many cases \vdash_L corresponds to validity in a class of frames K .

- Minimum modal logic K:

$$\vdash_K A \text{ iff } K \models A \quad (K \text{ is the class of all frames}).$$

- Modal logic K4 ($\Box x \rightarrow \Box \Box x$)

$$\vdash_{K4} A \text{ iff } T \models A \quad (T \text{ is the class of all transitive frames.})$$

There are modal logics that cannot be obtained from a class of Kripke frames [VB84].

Correspondence with DLs [Sch91]

The DL \mathcal{ALC} is a notational variant of K_m (K plus m modal parameters).

Correspondence with DLs [Sch91]

The DL \mathcal{ALC} is a notational variant of K_m (K plus m modal parameters).

- Bijective translation between \mathcal{ALC} concepts C and K_m formulas A_C .

Correspondence with DLs [Sch91]

The DL \mathcal{ALC} is a notational variant of K_m (K plus m modal parameters).

- Bijective translation between \mathcal{ALC} concepts C and K_m formulas A_C .

$$A \rightarrow x_A \quad r_i \rightarrow \text{modal parameter } p_i \quad \forall r_i \rightarrow \square_{p_i}$$

Correspondence with DLs [Sch91]

The DL \mathcal{ALC} is a notational variant of K_m (K plus m modal parameters).

- Bijective translation between \mathcal{ALC} concepts C and K_m formulas A_C .

$$A \rightarrow x_A \quad r_i \rightarrow \text{modal parameter } p_i \quad \forall r_i \rightarrow \Box_{p_i}$$

- Bijective translation between interpretations and Kripke models:

$$\mathcal{I} \rightarrow M_{\mathcal{I}} \text{ s.t.: } A^{\mathcal{I}} = V_{M_{\mathcal{I}}}(x_A) \quad \text{and} \quad (r_i)^{\mathcal{I}} = R_{p_i}.$$

Correspondence with DLs [Sch91]

The DL \mathcal{ALC} is a notational variant of K_m (K plus m modal parameters).

- Bijective translation between \mathcal{ALC} concepts C and K_m formulas A_C .

$$A \rightarrow x_A \quad r_i \rightarrow \text{modal parameter } p_i \quad \forall r_i \rightarrow \Box_{p_i}$$

- Bijective translation between interpretations and Kripke models:

$$\mathcal{I} \rightarrow M_{\mathcal{I}} \text{ s.t.: } A^{\mathcal{I}} = V_{M_{\mathcal{I}}}(x_A) \quad \text{and} \quad (r_i)^{\mathcal{I}} = R_{p_i}.$$

- Inference problems

A_C is valid in K_m **iff** $C \equiv \top$

$C \equiv D$ **iff** $A_C \leftrightarrow A_D$ is valid in K_m .

Unification in Modal Logics

- Let L be a modal logic. The unification problem in L is defined as follows.

Instance: A formula A in L .

Question: Is there a substitution σ such that $\vdash_L \sigma(A)$?

Unification in Modal Logics

- Let L be a modal logic. The unification problem in L is defined as follows.

Instance: A formula A in L .

Question: Is there a substitution σ such that $\vdash_L \sigma(A)$?

The set of all unifiers of A in L is denoted as $U_L(A)$.

Unification in Modal Logics

- Let L be a modal logic. The unification problem in L is defined as follows.

Instance: A formula A in L .

Question: Is there a substitution σ such that $\vdash_L \sigma(A)$?

The set of all unifiers of A in L is denoted as $U_L(A)$.

- Unifiers are ordered using the relation \leq_L^x .

Unification in Modal Logics

- Let L be a modal logic. The unification problem in L is defined as follows.

Instance: A formula A in L .

Question: Is there a substitution σ such that $\vdash_L \sigma(A)$?

The set of all unifiers of A in L is denoted as $U_L(A)$.

- Unifiers are ordered using the relation $\leq_L^{\mathcal{X}}$.

σ is more general than τ w.r.t. the variables in \mathcal{X}

iff

$\exists \theta$ such that $\vdash_L \tau(X) \leftrightarrow \theta(\sigma(X))$, for all $X \in \mathcal{X}$.

Unification in Modal Logics

- Let L be a modal logic. The unification problem in L is defined as follows.

Instance: A formula A in L .

Question: Is there a substitution σ such that $\vdash_L \sigma(A)$?

The set of all unifiers of A in L is denoted as $U_L(A)$.

- Unifiers are ordered using the relation $\leq_L^{\mathcal{X}}$.

σ is more general than τ w.r.t. the variables in \mathcal{X}

iff

$\exists \theta$ such that $\vdash_L \tau(X) \leftrightarrow \theta(\sigma(X))$, for all $X \in \mathcal{X}$.

- Unification type of A : defined w.r.t. $(U_L(A), \leq_L^{Vars(A)})$.

Unification - MLs vs DLs

Unification - MLs vs DLs

Slightly different definitions:

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

DLs: find σ such that $\sigma(C) \equiv \sigma(D)$.

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

DLs: find σ such that $\sigma(C) \equiv \sigma(D)$.

They “coincide” (if \leftrightarrow is expressible in the logic):

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

DLs: find σ such that $\sigma(C) \equiv \sigma(D)$.

They “coincide” (if \leftrightarrow is expressible in the logic):

From \mathcal{ALC} to K_m : $\sigma(C) \equiv \sigma(D)$ **iff** $\vdash_{K_m} \sigma(A_C) \leftrightarrow \sigma(A_D)$ **iff** $\vdash_{K_m} \sigma(A_C \leftrightarrow A_D)$.

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

DLs: find σ such that $\sigma(C) \equiv \sigma(D)$.

They “coincide” (if \leftrightarrow is expressible in the logic):

From \mathcal{ALC} to K_m : $\sigma(C) \equiv \sigma(D)$ **iff** $\vdash_{K_m} \sigma(A_C) \leftrightarrow \sigma(A_D)$ **iff** $\vdash_{K_m} \sigma(A_C \leftrightarrow A_D)$.

From K_m to \mathcal{ALC} : $\vdash_{K_m} \sigma(A)$ **iff** $\sigma(A) \equiv \top$.

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

DLs: find σ such that $\sigma(C) \equiv \sigma(D)$.

They “coincide” (if \leftrightarrow is expressible in the logic):

From \mathcal{ALC} to K_m : $\sigma(C) \equiv \sigma(D)$ **iff** $\vdash_{K_m} \sigma(A_C) \leftrightarrow \sigma(A_D)$ **iff** $\vdash_{K_m} \sigma(A_C \leftrightarrow A_D)$.

From K_m to \mathcal{ALC} : $\vdash_{K_m} \sigma(A)$ **iff** $\sigma(A) \equiv \top$.

Yet another subtle/significant difference

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

DLs: find σ such that $\sigma(C) \equiv \sigma(D)$.

They “coincide” (if \leftrightarrow is expressible in the logic):

From \mathcal{ALC} to K_m : $\sigma(C) \equiv \sigma(D)$ **iff** $\vdash_{K_m} \sigma(A_C) \leftrightarrow \sigma(A_D)$ **iff** $\vdash_{K_m} \sigma(A_C \leftrightarrow A_D)$.

From K_m to \mathcal{ALC} : $\vdash_{K_m} \sigma(A)$ **iff** $\sigma(A) \equiv \top$.

Yet another subtle/significant difference

- For DLs, concept constants are allowed in the unification problem.

Unification - MLs vs DLs

Slightly different definitions:

ML: find σ such that $\vdash_L \sigma(A)$.

DLs: find σ such that $\sigma(C) \equiv \sigma(D)$.

They “coincide” (if \leftrightarrow is expressible in the logic):

From \mathcal{ALC} to K_m : $\sigma(C) \equiv \sigma(D)$ **iff** $\vdash_{K_m} \sigma(A_C) \leftrightarrow \sigma(A_D)$ **iff** $\vdash_{K_m} \sigma(A_C \leftrightarrow A_D)$.

From K_m to \mathcal{ALC} : $\vdash_{K_m} \sigma(A)$ **iff** $\sigma(A) \equiv \top$.

Yet another subtle/significant difference

- For DLs, concept constants are allowed in the unification problem.
- For MLs, all variables are eligible to be substituted.

Unification - MLs vs DLs

Variables vs. Constants

Unification - MLs vs DLs

Variables vs. Constants

Unification in MLs can be seen as particular case of unification in DLs.

Unification - MLs vs DLs

Variables vs. Constants

Unification in MLs can be seen as particular case of unification in DLs.

- An algorithm to solve the problem in a DL, solves the problem in its ML variant.

Unification - MLs vs DLs

Variables vs. Constants

Unification in MLs can be seen as particular case of unification in DLs.

- An algorithm to solve the problem in a DL, solves the problem in its ML variant.
- A lower bound for the unification problem in a ML also applies to the corresponding DL (if any).

Unification - MLs vs DLs

Variables vs. Constants

Unification in MLs can be seen as particular case of unification in DLs.

- An algorithm to solve the problem in a DL, solves the problem in its ML variant.
- A lower bound for the unification problem in a ML also applies to the corresponding DL (if any).

Single equation vs. a system of equations

Unification - MLs vs DLs

Variables vs. Constants

Unification in MLs can be seen as particular case of unification in DLs.

- An algorithm to solve the problem in a DL, solves the problem in its ML variant.
- A lower bound for the unification problem in a ML also applies to the corresponding DL (if any).

Single equation vs. a system of equations

- In DLs, $\{C_1 \equiv? D_1, \dots, C_n \equiv? D_n\}$ can be transformed into:
$$\{\forall r_1.C_1 \sqcap \dots \sqcap \forall r_n.C_n \equiv? \forall r_1.D_1 \sqcap \dots \sqcap \forall r_n.D_n\}.$$

Unification - MLs vs DLs

Variables vs. Constants

Unification in MLs can be seen as particular case of unification in DLs.

- An algorithm to solve the problem in a DL, solves the problem in its ML variant.
- A lower bound for the unification problem in a ML also applies to the corresponding DL (if any).

Single equation vs. a system of equations

- In DLs, $\{C_1 \equiv? D_1, \dots, C_n \equiv? D_n\}$ can be transformed into:
$$\{\forall r_1. C_1 \sqcap \dots \sqcap \forall r_n. C_n \equiv? \forall r_1. D_1 \sqcap \dots \sqcap \forall r_n. D_n\}.$$
- In uni-modal logics, like K, the previous trick is not possible. However,
 σ solves $\{A_1, \dots, A_n\}$ iff it solves $\{A_1 \wedge \dots \wedge A_n\}$.

Motivation for unification in MLs

Unification in MLs is a special case of the [recognizability of admissible rules](#) problem.

Motivation for unification in MLs

Unification in MLs is a special case of the **recognizability of admissible rules** problem.

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

A positive answer means that $\frac{A}{B}$ can be added to L without changing the logic.

Motivation for unification in MLs

Unification in MLs is a special case of the **recognizability of admissible rules** problem.

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

A positive answer means that $\frac{A}{B}$ can be added to L without changing the logic.

How can unification help?

Motivation for unification in MLs

Unification in MLs is a special case of the **recognizability of admissible rules** problem.

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

A positive answer means that $\frac{A}{B}$ can be added to L without changing the logic.

How can unification help?

- It is a particular instance of the admissibility problem:

Motivation for unification in MLs

Unification in MLs is a special case of the **recognizability of admissible rules** problem.

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

A positive answer means that $\frac{A}{B}$ can be added to L without changing the logic.

How can unification help?

- It is a particular instance of the admissibility problem:

$\exists \sigma$ s.t. $\vdash_L \sigma(A)$ **iff** the rule $\frac{A}{\perp}$ is not admissible.

Motivation for unification in MLs

Unification in MLs is a special case of the **recognizability of admissible rules** problem.

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

A positive answer means that $\frac{A}{B}$ can be added to L without changing the logic.

How can unification help?

- It is a particular instance of the admissibility problem:

$\exists \sigma$ s.t. $\vdash_L \sigma(A)$ **iff** the rule $\frac{A}{\perp}$ is not admissible.

lower bounds/undecidability of unification transfer to the admissibility problem.

Motivation for unification in MLs

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

Motivation for unification in MLs

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

How can unification help?

Motivation for unification in MLs

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

How can unification help?

- In certain cases unification can be used to solve the admissibility problem.

Motivation for unification in MLs

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

How can unification help?

- In certain cases unification can be used to solve the admissibility problem.

Suppose a modal logic L has:

- finitary unification type.
- there is an effective algorithm computing a complete set of unifiers for a unification problem A .

Motivation for unification in MLs

Recognizability of admissible rules

Instance: A modal logic L and a rule $\frac{A}{B}$.

Question: Does $\vdash_L \sigma(A)$ implies $\vdash_L \sigma(B)$ for every substitution σ ?

How can unification help?

- In certain cases unification can be used to solve the admissibility problem.

Suppose a modal logic L has:

- finitary unification type.
- there is an effective algorithm computing a complete set of unifiers for a unification problem A .

Then,

$\frac{A}{B}$ is admissible
iff
 $\vdash_L \sigma(B)$ for all $\sigma \in U_L(A)$.

Some results

Some results

Positive results

- For $K4$, $S4$ and other modal systems:

Some results

Positive results

- For $K4$, $S4$ and other modal systems:
 - Unification is finitary and finite complete sets of unifiers can be computed.

Some results

Positive results

- For K4, S4 and other modal systems:
 - Unification is finitary and finite complete sets of unifiers can be computed.
 - Recognizability of admissible rules is decidable.

Some results

Positive results

- For $K4$, $S4$ and other modal systems:
 - Unification is finitary and finite complete sets of unifiers can be computed.
 - Recognizability of admissible rules is decidable.

Negative results [WZ08]

Some results

Positive results

- For $K4$, $S4$ and other modal systems:
 - Unification is finitary and finite complete sets of unifiers can be computed.
 - Recognizability of admissible rules is decidable.

Negative results [WZ08]

- Undecidable for any modal logic L with **universal modality** between K_U and $K4_U$.

Some results

Positive results

- For $K4$, $S4$ and other modal systems:
 - Unification is finitary and finite complete sets of unifiers can be computed.
 - Recognizability of admissible rules is decidable.

Negative results [WZ08]

- Undecidable for any modal logic L with **universal modality** between K_U and $K4_U$.
- Implies undecidability of unification in expressive and relevant DLs, like $SHIQ$.

Some results

Positive results

- For $K4$, $S4$ and other modal systems:
 - Unification is finitary and finite complete sets of unifiers can be computed.
 - Recognizability of admissible rules is decidable.

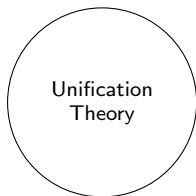
Negative results [WZ08]

- Undecidable for any modal logic L with **universal modality** between K_U and $K4_U$.
- Implies undecidability of unification in expressive and relevant DLs, like $SHIQ$.

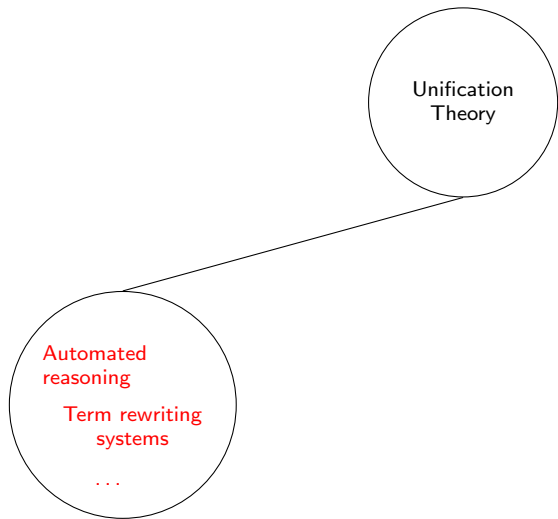
Main open problem

- Unification and admissibility in K . **K has unification type zero [Jer15]!**

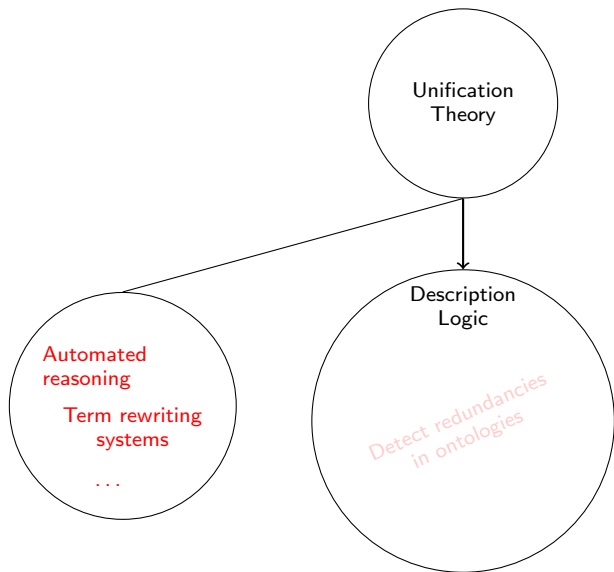
General summary



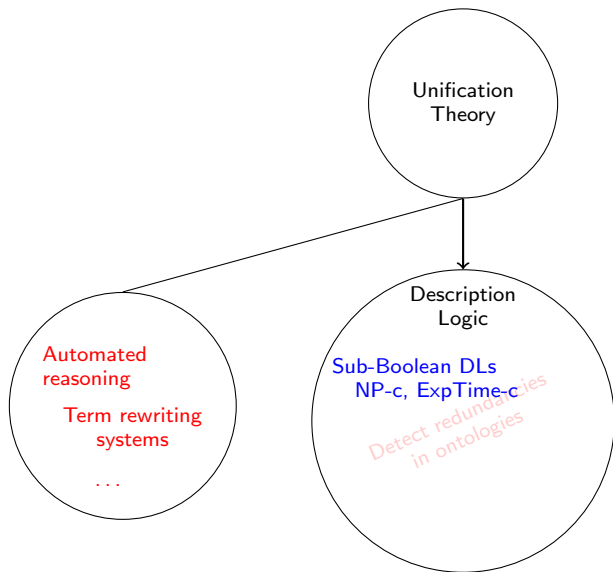
General summary



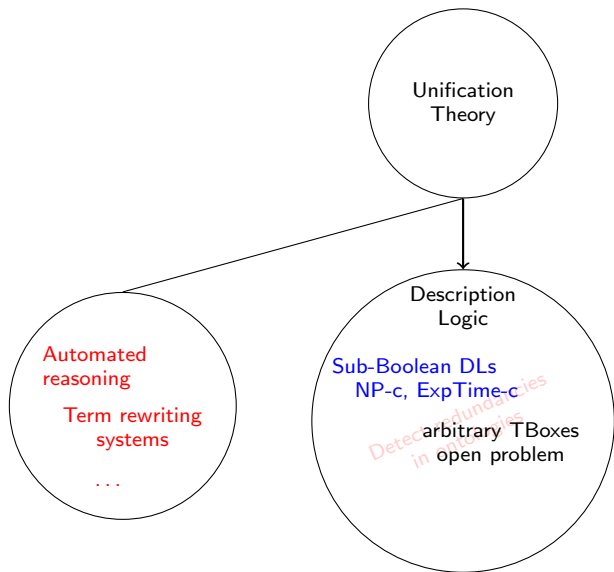
General summary



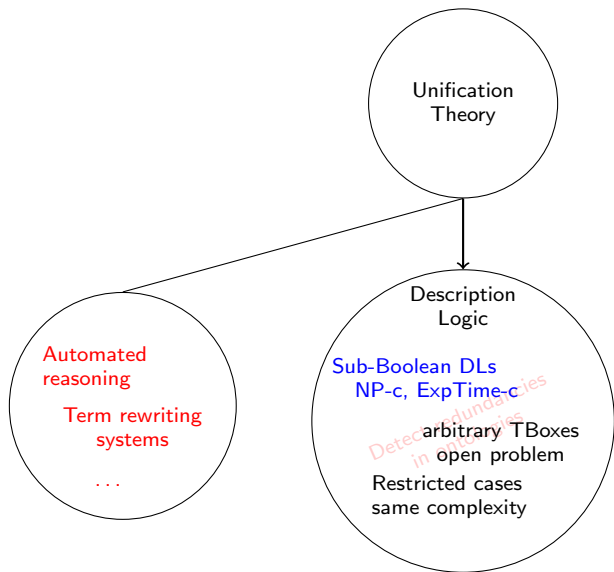
General summary



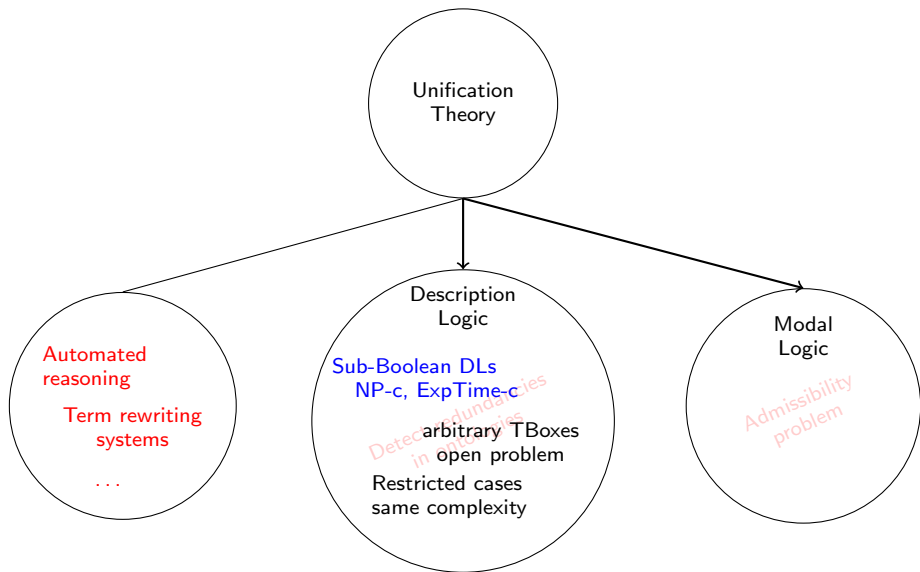
General summary



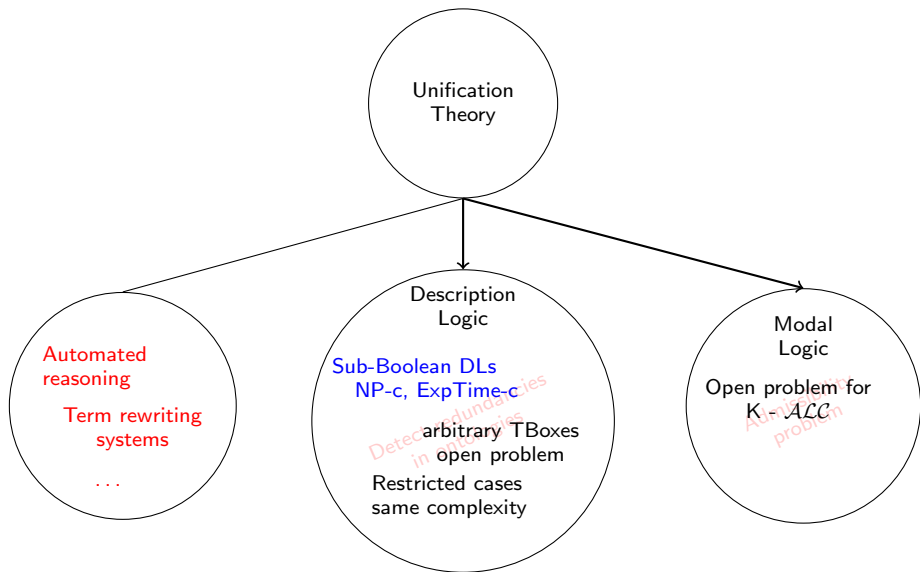
General summary



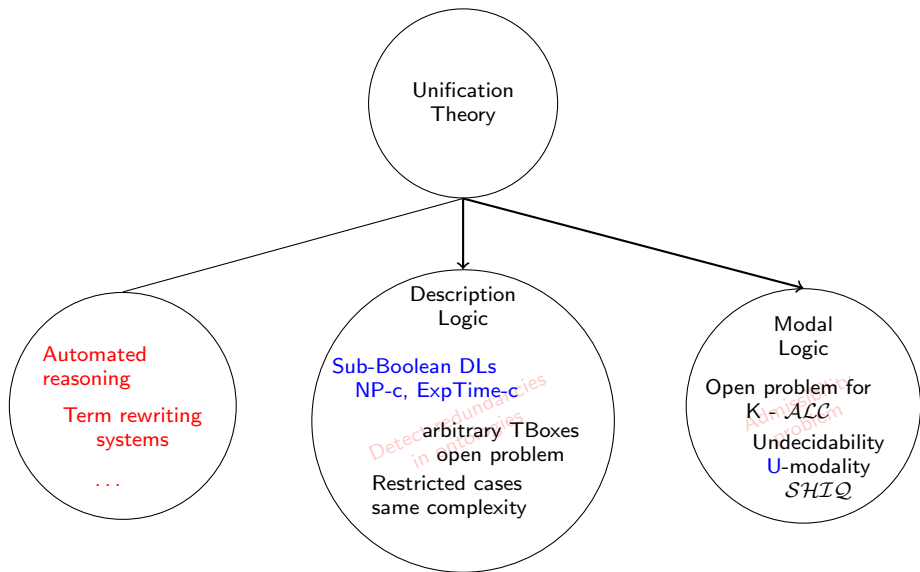
General summary



General summary



General summary



References I



Emil Jerábek.

Blending margins: the modal logic K has nullary unification type.

J. Log. Comput., 25(5):1231–1240, 2015.



Klaus Schild.

A correspondence theory for terminological logics: Preliminary report.

In *Proceedings of the 12th International Joint Conference on Artificial Intelligence. Sydney, Australia, August 24–30, 1991*, pages 466–471. Morgan Kaufmann, 1991.



Johan Van Benthem.

Correspondence Theory, pages 167–247.

Springer Netherlands, 1984.



Frank Wolter and Michael Zakharyashev.

Undecidability of the unification and admissibility problems for modal and description logics.

ACM Trans. Comput. Log., 9(4):25:1–25:20, 2008.