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Unification of Concept Terms in Description Logics: Revised Version

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Unification of Concept Terms in Description Logics: Revised Version

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Abstract

Unification of concept terms is a new kind of inference problem for Description Logics, which extends the equivalence problem by allowing to replace certain concept names by concept terms before testing for equivalence. We show that this inference problem is of interest for applications, and present first decidability and complexity results for a small concept description language.

1 Introduction

Knowledge representation languages based on Description Logics (DL languages) can be used to represent the terminological knowledge of an application domain in a structured and formally well-understood way [8, 3]. With the help of these languages, the important notions of the domain can be described by *concept terms*, i.e., expressions that are built from atomic concepts (unary predicates) and atomic roles (binary predicates) using the concept constructors provided

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by the DL language. The atomic concepts and concept terms represent sets of individuals, whereas roles represent binary relations between individuals. For example, using the atomic concept Woman and the atomic role child, the concept of all women having only daughters (i.e., women such that all their children are again women) can be represented by the concept term

Woman □ ∀child.Woman.

Knowledge representation systems based on Description Logics provide their users with various inference capabilities that allow them to deduce implicit knowledge from the explicitly represented knowledge. For instance, the *subsumption* algorithm allows one to determine subconcept-superconcept relationships: C is subsumed by D ($C \sqsubseteq D$) iff all instances of C are also instances of D, i.e., the first term is always interpreted as a subset of the second term. For example, the concept term Woman obviously subsumes the concept term Woman $\sqcap \forall \mathsf{child}.\mathsf{Woman}.$ With the help of the subsumption algorithm, a newly introduced concept term can automatically be placed at the correct position in the hierarchy of the already existing concept terms.

Two concept terms C, D are equivalent $(C \equiv D)$ iff they subsume each other, i.e., iff they always represent the same set of individuals. For example, the terms Woman $\sqcap \forall \mathsf{child}.\mathsf{Woman}$ and $(\forall \mathsf{child}.\mathsf{Woman}) \sqcap \mathsf{Woman}$ are equivalent since \sqcap is interpreted as set intersection, which is obviously commutative. The equivalence test can, for example, be used to find out whether a concept term representing a particular notion has already been introduced, thus avoiding multiple introduction of the same concept into the concept hierarchy. Unification of concept terms extends this inference capability by allowing to replace certain concept names by concept terms before testing for equivalence.

The first motivation for considering unification of concept terms comes from an application in chemical process engineering [5]. In this application, the DL system is used to support the design of a large terminology of concepts describing parts of chemical plants as well as processes that take place in these plants. Since several knowledge engineers are involved in defining new concepts, and since this knowledge acquisition process takes rather long (several years), it happens that the same (intuitive) concept is introduced several times, often with slightly differing descriptions. Our goal was to use the reasoning capabilities of the DL system (in particular, testing for equivalence of concept terms) to support avoiding this kind of redundancy. However, testing for equivalence of concepts is not always sufficient to find out whether, for a given concept term, there already exists another concept term in the knowledge base describing the same notion. For example, assume that one knowledge engineer has defined the concept of all women having only daughters¹ by the concept term

Woman □ ∀child.Woman.

 $^{^{1}\}mathrm{We}$ use an example from the family domain since examples from process engineering would require too much explanation.

A second knowledge engineer might represent this notion in a somewhat more fine-grained way, e.g., by using the term $\mathsf{Female} \sqcap \mathsf{Human}$ in place of Woman . The concept terms $\mathsf{Woman} \sqcap \forall \mathsf{child}. \mathsf{Woman}$ and

Female \sqcap Human \sqcap \forall child.(Female \sqcap Human)

are not equivalent, but they are meant to represent the same concept. The two terms can obviously be made equivalent by replacing the atomic concept Woman in the first term by the concept term Female \sqcap Human. This leads us to unification of concept terms, i.e., the question whether two concept terms C, D can be made equivalent by applying an appropriate substitution σ , where a substitution replaces (some of the) atomic concepts by concept terms. A substitution is a unifier of C, D iff $\sigma(C) \equiv \sigma(D)$. Of course, it is not necessarily the case that unifiable concept terms are meant to represent the same notion. A unifiability test can, however, suggest to the knowledge engineer possible candidate terms.

Another motivation for considering unification of concept terms comes from the work of Borgida and McGuinness [7], who introduce matching of concept terms (of the DL language used by the CLASSIC system) modulo subsumption: for given concept terms C and D they ask for a substitution σ such that $C \sqsubseteq \sigma(D)$. More precisely, they are interested in finding "minimal" substitutions for which this is the case, i.e., σ should satisfy the property that there does not exist another substitution δ such that $C \sqsubseteq \delta(D) \sqsubset \sigma(D)$. Since $C \sqsubseteq D$ iff $C \sqcap D \equiv C$, this matching problem can be reduced to a unification problem.

In the following, we consider the unification problem for a rather small DL language, called \mathcal{FL}_0 in the literature [2]. We shall see that this problem can be viewed as a unification problem modulo an appropriate equational theory: the theory ACUIh of a binary associative, commutative, and idempotent function symbol with a unit and several homomorphisms. This theory turns out to be a so-called commutative (or monoidal) theory [1, 13, 4], in which unification can be reduced to solving equations in a corresponding semiring, which in the case of ACUIh is the polynomial semiring (in non-commuting indeterminates) over the Boolean semiring.² The problem of solving linear equations over this semiring can in turn be reduced to a certain formal language problem, which can be solved using automata on finite trees. This provides us with an exponential time algorithm for deciding solvability of ACUIh-unification problems, and thus also for unification of concept terms of the DL language \mathcal{FL}_0 . We can also show that this is the best wee can do since the problem is Exptime-hard. Finally, we consider the matching problem for \mathcal{FL}_0 -concept terms, and show that it is decidable in polynomial time.

²Note that this is not the Boolean ring (with operations conjunction and ex-or), but the Boolean semiring (with operations conjunction and disjunction).

2 The DL language \mathcal{FL}_0

In this section, we introduce syntax and semantics of the knowledge representation language \mathcal{FL}_0 , and give a formal definition of subsumption, equivalence, and unification of concept terms.

Definition 1 Let \mathcal{C} and \mathcal{R} be disjoint finite sets, the set of atomic concepts and the set of atomic roles. The set of all \mathcal{FL}_0 -concept terms over \mathcal{C} and \mathcal{R} is inductively defined as follows:

- \bullet Every element of $\mathcal C$ is a concept term (atomic concept).
- The symbol \top is a concept term (top concept).
- If C and D are concept terms, then $C \sqcap D$ are concept terms (concept conjunction).
- If C is a concept term and R is an atomic role (i.e., $R \in \mathcal{R}$), then $\forall R.C$ is a concept term (value restriction).

The following definition provides a model-theoretic semantics for \mathcal{FL}_0 :

Definition 2 An interpretation I consists of a nonempty set Δ^I , the domain of the interpretation, and an interpretation function that assigns to every atomic concept $A \in \mathcal{C}$ a set $A^I \subseteq \Delta^I$, and to every atomic role $R \in \mathcal{R}$ a binary relation $R^I \subseteq \Delta^I \times \Delta^I$. The interpretation function is extended to complex concept terms as follows:

$$\begin{array}{rcl} \top^I &:=& \Delta^I, \\ (C \sqcap D)^I &:=& C^I \cap D^I, \\ (\forall R.C)^I &:=& \{d \in \Delta^I \mid \forall e \in \Delta^I \colon (d,e) \in R^I \rightarrow e \in C^I \}. \end{array}$$

Based on this semantics, subsumption and equivalence of concept terms is defined as follows: Let C and D be \mathcal{FL}_0 -concept terms.

- C is subsumed by D (C \sqsubseteq D) iff $C^I \subseteq D^I$ for all interpretations I.
- C is equivalent to D ($C \equiv D$) iff $C^I = D^I$ for all interpretations I.

In order to define unification of concept terms, we must first introduce the notion of a substitution operating on concept terms. To this purposes, we partition the set of atomic concepts into a set C_v of concept variables (which may be replaced by substitutions) and a set C_c of concept constants (which must not be replaced

by substitutions). Intuitively, C_v are the atomic concepts that have possibly been given another name or been specified in more detail in another concept term describing the same notion. The elements of C_c are the ones of which it is assumed that the same name is used by all knowledge engineers (e.g., standardized names in a certain domain).

A substitution σ is a mapping from C_v into the set of all \mathcal{FL}_0 -concept terms. This mapping is extended to concept terms in the obvious way, i.e.,

- $\sigma(A) := A \text{ for all } A \in \mathcal{C}_c$,
- $\sigma(\top) := \top$,
- $\sigma(C \sqcap D) := \sigma(C) \sqcap \sigma(D)$, and
- $\sigma(\forall R.C) := \forall R.\sigma(C)$.

Definition 3 Let C and D be \mathcal{FL}_0 -concept terms. The substitution σ is a unifier of C and D iff $\sigma(C) \equiv \sigma(D)$. In this case, the concept terms C and D are called unifiable.

For example, if $A \in \mathcal{C}_c$ and $X, Y \in \mathcal{C}_v$, then $\sigma = \{X \mapsto A \sqcap \forall S.A, Y \mapsto \forall R.A\}$ is a unifier of the concept terms $\forall R. \forall R.A \sqcap \forall R.X$ and $Y \sqcap \forall R.Y \sqcap \forall R. \forall S.A$.

3 The equational theory ACUIh

Unification of \mathcal{FL}_0 -concept terms can be reduced to the well-known notion of unification modulo an equational theory, which allows us to employ methods and results developed in unification theory [6].

First, we show how concept terms can be translated into terms over an appropriate signature $\Sigma_{\mathcal{R}}$, which consists of a binary function symbol \wedge , a constant symbol T , and for each $R \in \mathcal{R}$ a unary function symbol h_R . In addition, every element of \mathcal{C}_v is considered as variable symbol, and every element of \mathcal{C}_c as a (free) constant. The translation function τ is defined by induction on the structure of concept terms:

- $\tau(A) := A \text{ for all } A \in \mathcal{C},$
- $\tau(\top) := \mathsf{T}$,
- $\tau(C \sqcap D) := \tau(C) \land \tau(D)$, and
- $\tau(\forall R.C) := h_R(\tau(C)).$

Obviously, τ is a bijective mapping between the set of all \mathcal{FL}_0 -concept terms (with atomic concepts from $\mathcal{C} = \mathcal{C}_v \cup \mathcal{C}_c$ and atomic roles from \mathcal{R}) and the set of all terms over the signature $\Sigma_{\mathcal{R}}$ built using variables from \mathcal{C}_v and free constants from \mathcal{C}_c .

The equational theory ACUIh that axiomatizes equivalence of \mathcal{FL}_0 -concept terms consists of the following identities:

ACUIh := {
$$(x \wedge y) \wedge z = x \wedge (y \wedge z), x \wedge y = y \wedge x, x \wedge x = x, x \wedge T = x$$
 }
 $\cup \{ h_R(x \wedge y) = h_R(x) \wedge h_R(y), h_R(T) = T \mid R \in \mathcal{R} \}.$

Let $=_{\text{ACUIh}}$ denote the congruence relation on terms induced by ACUIh, i.e., $s =_{\text{ACUIh}} t$ holds iff s can be transformed into t using identities from ACUIh.

Lemma 4 Let C and D be \mathcal{FL}_0 -concept terms. Then

$$C \equiv D$$
 iff $\tau(C) =_{ACUIh} \tau(D)$.

Proof. The if-direction is an easy consequence of the semantics of \mathcal{FL}_0 -concept terms. In fact, since concept conjunction is interpreted as set intersection, it inherits associativity, commutativity, and idempotency (modulo equivalence) from set intersection. In addition, it is easy to see that $C \sqcap \top \equiv C$, $\forall R. \top \equiv \top$, and $\forall R. (C \sqcap D) \equiv (\forall R. C) \sqcap (\forall R. D)$ hold for arbitrary concept terms C and D.

To show the only-if-direction, we first represent \mathcal{FL}_0 -concept terms in a certain normal form. Using the equivalences noted in the proof of the if-direction, any \mathcal{FL}_0 -concept term can be transformed into an equivalent \mathcal{FL}_0 -concept term C' that is either \top or a (nonempty) conjunction of terms of the form $\forall R_1 \cdots \forall R_n. A$ for $n \geq 0$ (not necessarily distinct) role names R_1, \ldots, R_n and a concept name $A \neq \top$. Since the transformation into this normal form uses only identities from ACUIh, we have $\tau(C) =_{\text{ACUIh}} \tau(C')$.

Now, assume that $\tau(C) \neq_{\text{ACUIh}} \tau(D)$. Consequently, the corresponding normal forms C', D' also satisfy $\tau(C') \neq_{\text{ACUIh}} \tau(D')$. This implies that one of these two normal forms contains a conjunct $\forall R_1, \dots, \forall R_n, A \text{ (for } n \geq 0 \text{ and } A \neq \top \text{) that does not occur in the other normal form. We assume without loss of generality that this conjunct occurs in <math>C'$, but not in D'.

We use this conjunct to construct an interpretation I such that $C'^I \neq D'^I$, which implies $C' \not\equiv D'$ and thus $C \not\equiv D$. The domain Δ^I of this interpretation consists of n+1 distinct individuals d_0, \ldots, d_n . The interpretation of the concept names is given by $B^I := \Delta^I$ for all names $B \neq A$, and $A^I := \Delta^I \setminus \{d_n\}$. Finally, the role names are interpreted as $S^I := \{(d_{i-1}, d_i) \mid S = R_i\}$. As an obvious consequence of this definition, we obtain $d_0 \not\in (\forall R_1, \cdots, \forall R_n, A)^I$, and thus $d_0 \not\in C'^I = C^I$. On the other hand, $d_0 \in T^I$ and $d_0 \in (\forall S_1, \cdots, \forall S_m, B)^I$ for all concept terms of the form $\forall S_1, \cdots, \forall S_m, B$ that are different to $\forall R_1, \cdots, \forall R_n, A$. Consequently, $d_0 \in D'^I = D^I$.

As a consequence of this lemma, the concept terms C and D are unifiable iff the corresponding terms $\tau(C)$ and $\tau(D)$ are unifiable modulo ACUIh. For example, the concept terms $\forall R. \forall R. A \sqcap \forall R. X$ and $Y \sqcap \forall R. Y \sqcap \forall R. \forall S. A$ are translated into the terms $t_1 := h_R(h_R(a)) \land h_R(x)$ and $t_2 := y \land h_R(y) \land h_R(h_S(a))$, and the substitution $\sigma' := \{x \mapsto a \land h_S(a), y \mapsto h_R(a)\}$ is an ACUIh-unifier of these terms, i.e., $\sigma(t_1) =_{\text{ACUIh}} \sigma(t_2)$.

In unification theory, one usually considers unification problems that consist of a finite set of term equations $\Gamma = \{s_1 = t_1, ..., s_n = t_n\}$ rather than a single equation $s = t_n$. For ACUIh, we can show that the system Γ has an ACUIh-unifier iff the single equation

$$h_{R_1}(s_1) \wedge \cdots \wedge h_{R_n}(s_n) = h_{R_1}(t_1) \wedge \cdots \wedge h_{R_n}(t_n)$$

has an ACUIh-unifier, provided that h_{R_1}, \ldots, h_{R_n} are n distinct unary function symbols in $\Sigma_{\mathcal{R}}$. Thus, solving systems of equations is equivalent to solving a single equation in this case. The correctness of this reduction is an easy consequence of the following lemma.

Lemma 5 Let $C_1, \ldots, C_n, D_1, \ldots, D_n$ be \mathcal{FL}_0 -concept terms, and R_1, \ldots, R_n be n pairwise distinct role names. Then

$$\forall R_1.C_1 \sqcap \cdots \sqcap \forall R_n.C_n \equiv \forall R_1.D_1 \sqcap \cdots \sqcap \forall R_n.D_n \quad iff \quad C_1 \equiv D_1,\ldots,C_n \equiv D_n.$$

Proof. The if-direction of the lemma is trivially satisfied. In order to show the only-if-direction, assume that $C_i \not\equiv D_i$ for some $i, 1 \leq i \leq n$. Thus, there exists an interpretation I such that $C_i^I \not\equiv D_i^I$. We assume (without loss of generality) that there exists $d \in \Delta^I$ such that $d \in C_i^I \setminus D_i^I$. We extend the interpretation I to an interpretation I' by defining $\Delta^{I'} := \Delta^I \cup \{e\}$, where $e \not\in \Delta^I$. The interpretation in I' of all concept names and of all role names different from R_i coincides with their interpretation in I. Finally, $R_i^{I'} := R_i^I \cup \{(e,d)\}$. By construction of I', we have $e \not\in (\forall R_i.D_i)^{I'}$. In addition, $e \in (\forall R_j.C_j)^{I'}$ for all $j, 1 \leq j \leq n$. Thus, $e \in (\forall R_1.C_1 \sqcap \cdots \sqcap \forall R_n.C_n)^{I'}$, but $e \not\in (\forall R_1.D_1 \sqcap \cdots \sqcap \forall R_n.D_n)^{I'}$, which shows that the two terms are not equivalent.

For readers that are familiar with unification theory, we want to point out that the *unification type* of ACUIh has already been determined in [1]: ACUIh is of type zero, which means that ACUIh-unification problems need not have a minimal complete set of ACUIh-unifiers. In particular, this implies that there exist ACUIh-unification problems for which the set of all unifiers cannot be represented as the set of all instances of a *finite* set of unifiers. For our application in knowledge representation, this result seems not to be very relevant since we

³To distinguish between concept names in concept terms and variable and constant symbols in terms over $\Sigma_{\mathcal{R}}$, we use upper-case letters for concept names and the corresponding lower-case letters for constants and variables.

are mainly interested in ground solutions of the unification problems, i.e., in unifiers that do not introduce concept variables. In the present paper, we restrict our attention to the decision problem, i.e., the problem of deciding solvability of ACUIh-unification problems. This problem has not been considered in [1]. In the following, we will show that this problem is decidable. Note that unification in the closely related theory ACUh, which is obtained from ACUIh by removing the axiom $x \wedge x = x$, has been shown to be undecidable [12].

4 Reducing ACUIh-unification to solving linear equations

The purpose of this section is to show that ACUIh-unification can be reduced to solving the following formal language problem: Let $S_0, S_1, \ldots, S_n, T_0, T_1, \ldots, T_n$ be finite sets of words over the alphabet of all role names. We consider the equation

$$S_0 \cup S_1 X_1 \cup \dots \cup S_n X_n = T_0 \cup T_1 X_1 \cup \dots \cup T_n X_n. \quad (*)$$

A solution of this equation assigns finite sets of words to the variables X_i such that the equation holds. The operation \cup stands for set union and expressions like S_iX_i for element-wise concatenation of sets of words; e.g., $\{SR, S\}\{R, RR\} = \{SRR, SR, SRRR\}$.

This reduction can either be obtained directly, or as a consequence of results from unification theory. In the following, we consider both approaches.

4.1 Commutative theories and semirings

The theory ACUIh is a so-called commutative theory [1], for which solving unification problems can be reduced to solving systems of linear equations over a corresponding semiring [13, 4]. Conversely, every system of linear equations over this semiring corresponds to a unification problem.

Let us first consider the theory ACUI, which consists of the axioms specifying that \wedge is associative, commutative and idempotent, and that T is a unit element with respect to \wedge . The corresponding semiring is obtained by considering the ACUI-free algebra in one generator (say x), and then taking the set of all endomorphisms of this algebra. Since the ACUI-free algebra generated by x consists of two congruence classes, with representatives x and T, respectively, there are two possible endomorphisms: 0, which is defined by $x \mapsto T$, and 1, which is defined by $x \mapsto x$. The multiplication \cdot of this semiring is just composition of endomorphisms, and the addition + is obtained by applying \wedge argument-wise, e.g., $(1+0)(x) := 1(x) \wedge 0(x) = x \wedge T =_{\text{ACUI}} x = 1(x)$. It is easy to see that +

behaves like disjunction and · like conjunction on the truth values 0 and 1. Thus, the semiring corresponding to ACUI is the Boolean semiring.

As shown in [4], adding homomorphisms to a commutative theory corresponds to going to a polynomial semiring (in non-commuting indeterminates) on the semiring side, where every indeterminate corresponds to one of the homomorphisms. Thus, the semiring $\mathcal{S}_{\text{ACUIh}}$ corresponding to ACUIh is the polynomial semiring (in $|\mathcal{R}|$ non-commuting indeterminates) over the Boolean semiring. Let Δ be the set of these indeterminates (which are w.l.o.g. just the role names). Monomials in $\mathcal{S}_{\text{ACUIh}}$ are simply words over the alphabet Δ , and since the addition operation in the semiring is idempotent, the elements of the semiring can be seen as finite sets of words over this alphabet. Thus, the semiring $\mathcal{S}_{\text{ACUIh}}$ can be described as follows:

- its elements are finite sets of words (over the alphabet Δ of all role names),
- its addition operation is union of sets with the empty set \emptyset as unit,
- its multiplication operation is element-wise concatenation with the set $\{\varepsilon\}$ consisting of the empty word as unit.

As described in [13, 4], ACUIh-unification problems (consisting w.l.o.g. of a single equation) are now translated into (inhomogeneous) linear equations over this semiring. According to the above description of \mathcal{S}_{ACUIh} , these are just equations of the form (*). In the next section we explain in more detail how these equations can be obtained from a given unification problem.

4.2 A direct reduction to linear equations

The fact that equivalence of \mathcal{FL}_0 -concept terms can be axiomatized by a commutative equational theory has allowed us to employ known results from unification theory about the connection between unification modulo commutative theories and solving linear equations in semirings. In this subsection, we show how the linear equations corresponding to a unification problem between \mathcal{FL}_0 -concept terms can be obtained directly, without the detour through equational unification. On the one hand, this may be helpful for readers not familiar with the relevant literature in unification theory. On the other hand, it opens the possibility to use a similar approach for concept languages for which equivalence cannot be axiomatized by a commutative theory.

Let C, D be the two \mathcal{FL}_0 -concept terms to be unified, and assume that $\emptyset \neq \{A_1, \ldots, A_k\} \subseteq C_c$ contains all the concept names of C_c that occur in C, D. In addition, let X_1, \ldots, X_n be the concept names of C_v that occur in C, D.

First, we show that C, D can be transformed into a certain normal form. We know that any \mathcal{FL}_0 -concept term can be transformed into an equivalent \mathcal{FL}_0 -concept term that is either \top or a (nonempty) conjunction of terms of the form $\forall R_1, \dots, \forall R_m.A$ for $m \geq 0$ (not necessarily distinct) role names R_1, \dots, R_m and a concept name $A \neq \top$. We abbreviate $\forall R_1, \dots, \forall R_m.A$ by $\forall R_1, \dots, R_m.A$, where R_1, \dots, R_m is considered as a word over the alphabet of all role names Δ . In addition, instead of $\forall w_1.A \sqcap \dots \sqcap \forall w_\ell.A$ we write $\forall L.A$ where $L := \{w_1, \dots, w_\ell\}$ is a finite set of words over Δ . The term $\forall \emptyset.A$ is considered to be equivalent to \top . Using these abbreviations, the terms C, D can be rewritten as

$$C \equiv \forall S_{0,1}.A_1 \sqcap \ldots \sqcap \forall S_{0,k}.A_k \sqcap \forall S_1.X_1 \sqcap \ldots \sqcap \forall S_n.X_n,$$

$$D \equiv \forall T_{0,1}.A_1 \sqcap \ldots \sqcap \forall T_{0,k}.A_k \sqcap \forall T_1.X_1 \sqcap \ldots \sqcap \forall T_n.X_n,$$

for finite sets of words $S_{0,i}, S_j, T_{0,i}, T_j$ (i = 1, ..., k, j = 1, ..., n). If C, D are ground terms, i.e., \mathcal{FL}_0 -concept terms that do not contain concept variables, then we have $S_1 = ... = S_n = \emptyset = T_1 = ... = T_n$. In fact, the terms $\forall \emptyset. X_i$ are equivalent to \top , and can thus be removed from the conjunction.

The next lemma characterizes equivalence of ground terms in \mathcal{FL}_0 .

Lemma 6 Let C, D be ground terms such that

$$C \equiv \forall U_1.A_1 \sqcap \ldots \sqcap \forall U_k.A_k, D \equiv \forall V_1.A_1 \sqcap \ldots \sqcap \forall V_k.A_k.$$

Then $C \equiv D$ iff $U_i = V_i$ for all i = 1, ..., k.

Proof. The if-direction is trivial. To show the only-if-direction, assume that $U_i \neq V_i$. Without loss of generality, let $w = R_1 \dots R_r$ be such that $w \in U_i \setminus V_i$. Thus, the conjunct $\forall R_1 \dots \forall R_r. A_i$ occurs in C, but not in D. As in the proof of the only-if-direction of Lemma 4, this fact can be used to construct an interpretation I such that $D^I \setminus C^I \neq \emptyset$, which shows that the two terms cannot be equivalent. \square

As an easy consequence of this lemma, we can now characterize unifiability of \mathcal{FL}_0 -concept terms:

Theorem 7 Let C, D be \mathcal{FL}_0 -concept terms such that

$$C \equiv \forall S_{0,1}.A_1 \sqcap \ldots \sqcap \forall S_{0,k}.A_k \sqcap \forall S_1.X_1 \sqcap \ldots \sqcap \forall S_n.X_n, D \equiv \forall T_{0,1}.A_1 \sqcap \ldots \sqcap \forall T_{0,k}.A_k \sqcap \forall T_1.X_1 \sqcap \ldots \sqcap \forall T_n.X_n.$$

Then C, D are unifiable iff for all i = 1, ..., k, the linear equation $E_{C,D}(A_i)$:

$$S_{0,i} \cup S_1 X_{1,i} \cup \cdots \cup S_n X_{n,i} = T_{0,i} \cup T_1 X_{1,i} \cup \cdots \cup T_n X_{n,i}$$

has a solution.

Note that this is not a system of k equations that must be solved simultaneously: since they do not share variables, each of these equations can be solved separately.

Before proving the theorem, let us consider a simple example: The concept terms in normal form corresponding to

$$C = \forall R.(A_1 \sqcap \forall R.A_2) \sqcap \forall R.\forall S.X_1,$$

$$D = \forall R.\forall S.(\forall S.A_1 \sqcap \forall R.A_2) \sqcap \forall R.X_1 \sqcap \forall R.\forall R.A_2$$

are

$$C' = \forall \{R\}.A_1 \sqcap \forall \{RR\}.A_2 \sqcap \forall \{RS\}.X_1,$$

$$D' = \forall \{RSS\}.A_1 \sqcap \forall \{RSR, RR\}.A_2 \sqcap \forall \{R\}.X_1.$$

Thus, unification of C, D leads to the two linear equations

$$\{R\} \cup \{RS\}X_{1,1} = \{RSS\} \cup \{R\}X_{1,1},$$

 $\{RR\} \cup \{RS\}X_{1,2} = \{RSR, RR\} \cup \{R\}X_{1,2}.$

The first equation (the one for A_1) has $X_{1,1} = \{\varepsilon, S\}$ as a solution, and the second (the one for A_2) has $X_{1,2} = \{R\}$ as a solution. These two solutions yield the following unifier of C, D:

$$\{X_1 \mapsto A_1 \sqcap \forall S.A_1 \sqcap \forall R.A_2\}.$$

Proof of the theorem. It is easy to see that the unification problem for C, D has a solution iff it has a ground solution, i.e., a unifier that replaces the variables X_i by terms containing no other concept names than A_1, \ldots, A_k . In fact, in a given unifier, concept constants not occurring in C, D and concept variables can simply be instantiated by (arbitrary) ground terms. The obtained substitution is ground and still a unifier.

Now, let $\sigma := \{X_1 \mapsto \bigcap_{i=1}^k \forall U_{1,i}.A_i, \ldots, X_n \mapsto \bigcap_{i=1}^k \forall U_{n,i}.A_i\}$ be a ground substitution. Using the identities in ACUIh, it is easy to see that

$$\sigma(C) \equiv \bigcap_{i=1}^{k} \forall \left(S_{0,i} \cup S_{1} U_{1,i} \cup \cdots \cup S_{n} U_{n,i} \right) . A_{i},$$

$$\sigma(D) \equiv \bigcap_{i=1}^{k} \forall \left(T_{0,i} \cup T_{1} U_{1,i} \cup \cdots \cup T_{n} U_{n,i} \right) . A_{i}.$$

Lemma 6 implies that $\sigma(C) \equiv \sigma(D)$ iff, for all i = 1, ..., k,

$$S_{0,i} \cup S_1 U_{1,i} \cup \cdots \cup S_n U_{n,i} = T_{0,i} \cup T_1 U_{1,i} \cup \cdots \cup T_n U_{n,i}$$

Thus, if σ is a unifier of C, D, then $X_{1,i} := U_{1,i}, \ldots, X_{n,i} := U_{n,i}$ is a solution of $E_{C,D}(A_i)$ $(i = 1, \ldots, k)$. Conversely, solutions of $E_{C,D}(A_i)$ for $i = 1, \ldots, k$ can be used to build a unifier of C, D.

5 Solving linear equations in $\mathcal{S}_{\scriptscriptstyle ext{ACUIh}}$

In this section, we show that solvability of ACUIh-unification problems, and thus also unification of \mathcal{FL}_0 -concept terms, is decidable:

Theorem 8 Solvability of ACUIh-unification problems can be decided in deterministic exponential time.

This decidability result can be obtained by reducing solvability of linear equations in the semiring S_{ACUIh} to the emptiness problem for (root-to-frontier) tree automata working on finite trees [11]. The main idea underlying the proof is as follows. A finite set of words over an alphabet Δ of cardinality k can be represented by a finite tree, where each node has at most k sons. In such a tree, every path from the root to a node can be represented by a unique word over Δ . If the nodes of the tree are labelled with 0 or 1, then we can take the set of all words represented by the tree. In the following, we assume w.l.o.g. that $\Delta = \{1, \ldots, k\}$.

Definition 9 A k-ary tree with labels in $\{0,1\}$ is a mapping $t:dom(t) \to \{0,1\}$ such that dom(t) is a finite subset of $\{1,\ldots,k\}^*$ such that

- dom(t) is prefix-closed, i.e., $uv \in dom(t)$ implies $u \in dom(t)$.
- $ui \in dom(t)$ for some $i, 1 \le i \le k$, implies $uj \in dom(t)$ for all j = 1, ..., k.

The elements of dom(t) are the nodes of the tree t, and t(u) is called the label of node u. The empty word ε is the root of t, and the nodes u such that $ui \notin dom(t)$ for all $i = 1, \ldots, k$ are the leaves of t. The set of all leaves of t is called the frontier of t. Nodes of t that are not in the frontier are called inner nodes. If $ui \in dom(t)$ then it is called the ith son of u in t. By our definition of k-ary trees, any node of t is either a leaf, or it has exactly k sons.

For a k-ary tree t with labels in $\{0,1\}$ we define

$$L(t) := \{ u \in dom(t) \mid t(u) = 1 \}.$$

Obviously, L(t) is a finite set of words over $\Delta = \{1, \ldots, k\}$, and any finite set of words over Δ can be represented in this way.

Definition 10 A (nondeterministic) root-to-frontier (or top-down) tree automaton that works on k-ary trees with labels in $\{0,1\}$ is a 4-tuple $\mathcal{A} = (Q,I,T,F)$ where

• Q is a finite set of states,

- $I \subseteq Q$ is the set of initial states,
- $T \subseteq Q \times \{0,1\} \times Q^k$ is the transition relation, and
- $F: \{0,1\} \to 2^Q$ assigns to each label l in $\{0,1\}$ a set of final states $F(l) \subseteq Q$.

A run of \mathcal{A} on the tree t is a mapping $r: dom(t) \to Q$ such that

• $(r(u), t(u), r(u1), \dots, r(uk)) \in T$ for all inner nodes u.

The run r is called successful iff

- $r(\varepsilon) \in I$ (root condition),
- $r(u) \in F(t(u))$ for all leaves u (leaf condition).

The tree language accepted by A is defined as

$$\mathcal{L}(\mathcal{A}) := \{t \mid \text{there exists a successful run of } \mathcal{A} \text{ on } t\}.$$

The emptiness problem for \mathcal{A} is the question whether $\mathcal{L}(\mathcal{A}) \neq \emptyset$.

The following theorem is well-known (see, e.g., [15]):

Theorem 11 The emptiness problem for root-to-frontier tree automata is decidable in polynomial time.

Our approach for solving linear equations in \mathcal{S}_{ACUIh} with the help of tree automata cannot treat equations of the form

$$S_0 \cup S_1 X_1 \cup \cdots \cup S_n X_n = T_0 \cup T_1 X_1 \cup \cdots \cup T_n X_n$$
 (*)

directly:⁴ it needs an equation where the variables X_i are in front of the coefficients S_i . However, such an equation can easily be obtained from (*) by considering the mirror images (or reverse) of the involved languages. For a word $w = i_1 \dots i_m$, its mirror image is defined as $w^{mi} := i_m \dots i_1$, and for a finite set of words $L = \{w_1, \dots, w_\ell\}$, its mirror image is $L^{mi} := \{w_1^{mi}, \dots, w_\ell^{mi}\}$. Obviously, $X_1 = L_1, \dots, X_n = L_n$ is a solution of (*) iff $Y_1 = L_1^{mi}, \dots, Y_n = L_n^{mi}$ is a solution of the corresponding mirrored equation (**):

$$S_0^{mi} \cup Y_1 S_1^{mi} \cup \dots \cup Y_n S_n^{mi} = T_0^{mi} \cup Y_1 T_1^{mi} \cup \dots \cup Y_n T_n^{mi}. \quad (**)$$

In principle, we build a tree automaton that accepts the trees representing the finite sets of words obtained by instantiating this equation with its solutions. To

⁴Basically, this is due to Theorem 11.6, (b) in [15].

achieve this goal, the automaton guesses at each node whether it (more precisely, the path leading to it) belongs to one of the Y_i s (more precisely, to the set of words instantiated for Y_i), and then does the necessary book-keeping to make sure that the concatenation with the elements of S_i^{mi} and T_i^{mi} is realized: if S_i^{mi} contains a word w, and the automaton has decided that a given node κ belongs to Y_i , then if one starts at κ and follows the path corresponding to w, one must find a node with label 1. Vice versa, every label 1 in the tree must be justified this way. The same must hold for T_i^{mi} in place of S_i^{mi} . The size of the set of states of this automaton will turn out to be exponential in the the size of the equation (due to the necessary book-keeping). Since the emptiness problem for tree automata working on finite trees can be solved in polynomial time (in the size of the automaton), this will yield the exponential time algorithm claimed in Theorem 8.

Before we can define the automaton corresponding to the (solutions of) equation (**), we need some more notation. For a finite set of words S and a word u, we define $u^{-1}S := \{v \mid uv \in S\}$. The suffix closure of S is the set $suf(S) := \{u \mid \text{there exists } v \text{ such that } vu \in S\}$. Obviously, the cardinality of suf(S) is linear in the size of S (which is the sum of the length of the words in S), and $u^{-1}S \subseteq suf(S)$.

The root-to-frontier tree automaton $\mathcal{A}_{**} = (Q, I, T, F)$ corresponding to equation (**) is defined as follows:

• Let $M_L := suf(\bigcup_{i=0}^n S_i^{mi})$, $M_R := suf(\bigcup_{i=0}^n T_i^{mi})$ and $N := \{1, \ldots, n\}$. Then $Q := 2^N \times 2^{M_L} \times 2^{M_R}$, i.e., the states of \mathcal{A}_{**} are triples whose first component is a subset of the set of indices of the variables in (**), the second component is a finite set of words that are suffixes of words occurring on the left-hand side of (**), and the third component is a finite set of words that are suffixes of words occurring on the right-hand side of (**). Obviously, the size of Q is exponential in the size of equation (**).

Intuitively, the first component of a state "guesses" to which of the Y_i s the word represented by the current node of the tree belongs. The second component does the book-keeping for the left-hand side of the equation: if u is the word represented by the current node of the tree and v belongs to the second component of the state, then uv must belong to the (evaluated) left-hand side. The third component does the same for the right-hand side.

• The set of initial states is defined as

$$I := \{ (G, L, R) \mid \ G \subseteq N, \ L = S_0^{mi} \cup \bigcup_{i \in G} S_i^{mi}, \ R = T_0^{mi} \cup \bigcup_{i \in G} T_i^{mi} \}.$$

Intuitively, G is our initial guess which of the Y_i s contain the empty word. Every word in S_0^{mi} belongs to the (evaluated) left-hand side, and if $\varepsilon \in Y_i$, then every word in S_i^{mi} also belongs to the left-hand side.

• The transition relation T consists of all tuples

$$((G_0, L_0, R_0), l, (G_1, L_1, R_1), \dots, (G_k, L_k, R_k)) \in Q \times \{0, 1\} \times Q^k$$

such that

 $-\varepsilon \in L_0 \text{ iff } \varepsilon \in R_0 \text{ iff } l=1.$

This makes sure that the left-hand side is evaluated to the same set of words as the right-hand side, and that this is the set of words represented by the accepted tree.

- For i = 1, ..., k,

$$L_i = i^{-1}L_0 \cup \bigcup_{j \in G_i} S_j^{mi},$$

$$R_i = i^{-1}R_0 \cup \bigcup_{j \in G_i} T_j^{mi}.$$

This updates the book-keeping information: if $iu \in L_0$ then u must belong to L_i , the corresponding book-keeping component of the ith son of the current node. If G_i contains j, i.e., we have guessed that the word represented by the ith son belongs to Y_j , then the book-keeping component L_i of this son must also contain all elements of S_j^{mi} . The equation for R_i can be explained similarly.

• The assignment of sets of final states to labels is defined as follows:

$$F(0) := \{ (G, L, R) \mid L = R = \emptyset \},$$

$$F(1) := \{ (G, L, R) \mid L = R = \{ \varepsilon \} \}.$$

Again, this makes sure that the left-hand side is evaluated to the same set of words as the right-hand side, and that this is the set of words represented by the accepted tree.

Lemma 12 Let t be a k-ary tree with labels in $\{0,1\}$. Then the following are equivalent:

- 1. $t \in \mathcal{L}(\mathcal{A}_{**})$.
- 2. There are finite sets of words $\theta(Y_1), \ldots, \theta(Y_n)$ such that

$$S_0^{mi} \cup \theta(Y_1) S_1^{mi} \cup \dots \cup \theta(Y_n) S_n^{mi} = L(t) = T_0^{mi} \cup \theta(Y_1) T_1^{mi} \cup \dots \cup \theta(Y_n) T_n^{mi}.$$

Proof. If $t \in \mathcal{L}(\mathcal{A}_{**})$, then there exists a successful run of \mathcal{A}_{**} on t. From the first components of the states assigned to the nodes of t we can read off appropriate sets $\theta(Y_1), \ldots, \theta(Y_n)$: if the first component of the state assigned to the node κ

contains i, then the word represented by κ belongs to $\theta(Y_i)$. The definition of \mathcal{A}_{**} makes sure that this assignment of finite sets of words to the variables in (**) satisfies the equations in statement 2 of the lemma.

Conversely, if $\theta(Y_1), \ldots, \theta(Y_n)$ is an assignment of finite sets of words to the variables Y_i , then this assignment can be used to determine appropriate first components of states for a run of \mathcal{A}_{**} . Once these first components are fixed, an appropriate tree t and the full run of \mathcal{A}_{**} on t can be reconstructed. The fact that the equations in statement 2 are satisfied guarantees that this run exists and that it is successful.

As an immediate consequence of this lemma we obtain that equation (**) has a solution iff $\mathcal{L}(\mathcal{A}_{**}) \neq \emptyset$. Since the emptiness problem can be decided in time polynomial in the size of \mathcal{A}_{**} , and since \mathcal{A}_{**} is exponential in the size of (**), this completes the proof of Theorem 8.

6 ACUIh-unification is Exptime-hard

We show in this section that the ACUIh-unification problem is Exptime-hard. The reduction is from the intersection problem of deterministic root-to-frontier automata, which has been shown to be Exptime-complete by Seidl [14]. This problem can be described as follows: given a sequence $\mathcal{A}_1, \ldots, \mathcal{A}_n$ of deterministic root-to-frontier automata (drfa) over the same ranked alphabet Σ , decide whether there exists a tree t accepted by each of these automata. (Note that, as a consequence of Theorem 11, the problem is polynomial for any fixed number n of automata.)

In contrast to the k-ary trees with labels in $\{0,1\}$ considered in Section 5, we consider trees with labels in the ranked alphabet Σ , where the number of successors of a node is determined by the rank of its label. Obviously, such trees are simply representations of terms over the signature Σ . As shown by Seidl, it is sufficient to restrict the attention to trees of rank ≤ 2 . We represent such a tree by a set S(t) of words over the alphabet $\Sigma \cup \{1,2\}$, where each word describes a path from a leaf to the root of the tree. The symbols 1 and 2 are used to represent the left and the right son of a node, respectively. For example, the tree t := f(g(a,b),a) yields the set $S(t) := \{a1g1f, b2g1f, a2f\}$. More generally, for a symbol a of rank 0 we have $S(a) := \{a\}$, and for a symbol a of rank a and trees a and trees a and a union of finitely many such sets is called a union of tree sets.

The root-to-frontier automaton \mathcal{A} is deterministic iff

- the set of initial states consists of a single initial state q_0 ,
- for a given state q and symbol q of rank k there exists exactly one k-tuple

 (q_1, \ldots, q_k) such that (q, g, q_1, \ldots, q_k) belongs to the transition relation T of A. In this case we write $\delta_A(q, g) = (q_1, \ldots, q_k)$.

It should be noted that deterministic root-to-frontier automata are weaker than nondeterministic ones. For example, the language consisting of the trees (written in term notation) f(a,a) and f(b,b) cannot be accepted by a deterministic root-to-frontier automaton since a drfa accepting these two trees would also accept f(a,b) and f(b,a). It is easy to see that $\{f(a,a), f(b,b)\}$ can be accepted by a nondeterministic rfa (see [11], Example 2.11). More generally, the values assigned by a run r of a drfa to the nodes on a path from the root to a leaf in a given tree are uniquely determined by the labels of the nodes on the path. This fact will be important for our reduction.

In the following, we may (w.l.o.g.) assume that the alphabet contains exactly one symbol \sharp of rank 0 (i.e., all the leaves are labeled with \sharp), and that the drfa has exactly one final state q_f , i.e., the final assignment is $F(\sharp) = \{q_f\}$. In fact, we can simple turn the original symbols of rank 0 into symbols of rank 1, and add the new symbol \sharp of rank 0 to Σ . For a symbol a of original rank 0, the final assignment I(a) is replaced by a transition satisfying $\delta(q,a) = q_f$ iff $q \in F(a)$. Obviously, this transformation can be done such that the original automaton \mathcal{A} accepts the tree t iff the new automaton \mathcal{A}_{\sharp} accepts the modified tree t_{\sharp} that is obtained from t by adding a son labeled with \sharp to every leaf of t. If we apply this transformation to automata $\mathcal{A}_1, \ldots, \mathcal{A}_n$, then the resulting automata accept a common tree iff the original ones did.

Given such a drfa \mathcal{A} over Σ_{\sharp} with final state q_f and initial state q_0 , we consider the alphabet Δ that consists of $\Sigma := \Sigma_{\sharp} \setminus \{\sharp\}$, the states Q of \mathcal{A} , and $1, 2.^6$ We construct the following linear equation, where the variables $X, X_{(q,g)}$ range over finite sets of words over Δ :

$$\{q_f\}X \cup \bigcup_{(q,g)\in Q\times\Sigma} \{q\}X_{(q,g)} = \{q_0\} \cup \bigcup_{\delta(q,g)=(q_1,\dots,q_k)} \{q_11g,\dots,q_kkg\}X_{(q,g)} \qquad (*)$$

In order to show how solutions of (*) look like, we must generalize the notions "tree set" and "union of tree sets" to trees over the alphabet $\Sigma \cup Q$, where the states in Q are assumed to be symbols of rank 0. A tree over the alphabet $\Sigma \cup Q$ can be seen as a possible intermediate configuration of a run of the drfa on a given tree. Informally, a run starts with label q_0 at the root and then uses the transition function of the automaton to propagate states towards the frontier (i.e., the leaves of the tree). A tree over $\Sigma \cup Q$ is obtained by pruning branches of the tree and using the states assigned by the run as labels of the cutting points. For example, assume that f, g are binary symbols, and \sharp is the only nullary symbol.

⁵To be more precise, if $q \notin F(a)$, then $\delta(q, a)$ is a new non-accepting state which reproduces itself.

⁶Recall that we assume that 2 is the maximal rank of symbols in our trees.

Let $\delta(q_0, f) := (q_1, q_f)$ and $\delta(q_1, g) := (q_f, q_f)$. Then the unique run starting with q_0 at the root of the tree $f(g(\sharp, \sharp), \sharp)$ labels the root with q_0 , its left son with q_1 , and all leaves with q_f . Possible intermediate configurations obtained from this run are described by the trees q_0 , $f(q_1, q_f)$, and $f(g(q_f, q_f), q_f)$. Such a tree is called a run tree, and the tree set obtained from it is called run tree set. If all the leaves of a given run tree t are labeled with q_f , then the tree t^{\sharp} obtained from t by replacing the label q_f by \sharp is accepted by the drfa \mathcal{A} .

We claim that, for any solution θ of equation (*), the set $\{q_f\}\theta(X)$ is a union of run tree sets. Since the leaves of the run trees t generating this set are all labeled with q_f , this means that the corresponding trees t^{\sharp} are all accepted by the drfa \mathcal{A} , i.e., $\{q_f\}\theta(X) = \bigcup_{i=1}^m S(t_i)$ for run trees t_1, \ldots, t_m whose leaves are labeled with q_f , and thus the trees $t_1^{\sharp}, \ldots, t_m^{\sharp}$ are accepted by \mathcal{A} .

To prove the claim (and its converse), we consider a more general situation. Let T be a finite set of words over Δ . We consider the equation T(*) that is obtained from (*) by replacing $\{q_f\}X$ by T.

Lemma 13 Let θ be a solution of T(*). If w is a word of maximal length in

$$T \cup \bigcup_{(q,g) \in Q \times \Sigma} \{q\} \theta(X_{(q,g)}) = \{q_0\} \cup \bigcup_{\delta(q,g) = (q_1, \dots, q_k)} \{q_1 1g, \dots, q_k kg\} \theta(X_{(q,g)}),$$

then $w \in T$.

Proof. If $w \notin T$, then $w \in \bigcup_{(q,g)\in Q\times\Sigma} \{q\}\theta(X_{(q,g)})$. Consequently, w=qu for a word $u\in\theta(X_{(q,g)})$. This implies that, for some state q_i , the longer word q_iigu occurs on the right-hand side of the equation, which contradicts the maximality of w.

Lemma 14 Equation T(*) has a solution iff T is a union of run tree sets.

Proof. The if-direction is not hard to see. Thus, let us consider the onlyif direction, i.e., assume that θ is a solution of T(*). We proof the statement simultaneously for all finite sets T by induction on the size of the solution θ , where the size of θ is the sum of the cardinalities of the sets $\theta(X_{(q,g)})$. Note that this sum is a well-defined natural number since the sets $\theta(X_{(q,g)})$ are finite.

Let w be a word of maximal length in

$$T \cup \bigcup_{(q,g) \in Q \times \Sigma} \{q\} \theta(X_{(q,g)}) = \{q_0\} \cup \bigcup_{\delta(q,g) = (q_1, \dots, q_k)} \{q_1 1g, \dots, q_k kg\} \theta(X_{(q,g)}).$$

By Lemma 13 we know that $w \in T$. Again, note that such a maximal word exists since the sets $\theta(X_{(q,g)})$ are finite.

Case 1: If $w = q_0$, then the maximality of w implies that $\theta(X_{(q,g)}) = \emptyset$ for all pairs $(q,g) \in Q \times \Sigma$. Consequently, $T = \{q_0\}$, and this is obviously a union of run tree sets.

Case 2: Assume that $w = p_i if u$ for a word $u \in \theta(X_{(p,f)})$, let ℓ be the rank of f, and let $\delta(p,f) := (p_1, \ldots, p_\ell)$. Since w is of maximal length, all the words $p_j j f u$ for $j \in \{1, \ldots, \ell\}$ are of maximal length as well, and thus they are all contained in T.

We define a new substitution θ' and a new set T' as follows:

- $\theta'(X_{(p,f)}) := \theta(X_{(p,f)}) \setminus \{u\}$, and
- on all other variables θ' coincides with θ .

The set T' is obtained from T by

- adding pu,
- for each $j \in \{1, \dots, \ell\}$, removing $p_j j f u$ unless it is contained in $\bigcup_{\delta(q,g)=(q_1,\dots,q_k)} \{q_1 1 g, \dots, q_k k g\} \theta'(X_{(q,g)}).$

Obviously, the substitution θ' is smaller than the substitution θ . Thus, we can apply the induction hypothesis to T' provided that we can show that θ' solves T'(*).

The only difference between the old and the new right-hand side of the equation is that some of the words $p_j j f u$ may have been removed from the new right-hand side. However, in this case we have also removed these words from T'. In addition, they cannot occur in one of the sets $\{p_j\}\theta'(X_{(p_j,g)})$ since this would contradict the maximality of w.

On the left-hand side, the fact that pu does not occur in $\{p\}\theta'(X_{(p,f)})$ is compensated by the fact that $pu \in T'$. Thus, the only difference between the old and the new left-hand side is that some of the words $p_j j f u$ do not belong to T'. However, these are exactly the words that do not belong to the new right-hand side.

To sum up, we have shown that θ' solves T'(*), and thus we know by induction that T' is a union of run tree sets, i.e., $T' = S(t_1) \cup \ldots \cup S(t_m)$ for run trees t_1, \ldots, t_m . We want to show that T is also a union of run tree sets.

First, assume that $pu \notin T$. Thus, we have $T = (T' \setminus \{pu\}) \cup \{p_1 1 f u, \dots p_\ell \ell f u\}$. Let t_i be such that $pu \in S(t_i)$. Since $\delta(p, f) = (p_1, \dots, p_\ell)$, the tree t_i' that is obtained from t_i by replacing the leave corresponding to the word pu by the tree $f(p_1, \dots, p_\ell)$ is also a run tree. In addition, $S(t_i') = (S(t_i) \setminus \{pu\}) \cup \{p_1 1 f u, \dots p_\ell \ell f u\}$. Thus, if we replace every tree t_i with $pu \in S(t_i)$ by the corresponding tree t_i' , we can represent T as a union of run tree sets.

If $pu \in T$, then we simply add one of the trees t'_i without removing the corresponding tree t_i .

Now, let A_1, \ldots, A_n be a sequence of deterministic root-to-frontier automata. For each automaton, we construct the corresponding equation, where the variable X is the only one shared by the different equations. Let (i) denote the equation corresponding to A_i .

If there is a tree t_{\sharp} that is accepted by each of these automata, then the tree t that is obtained from t_{\sharp} by replacing \sharp by q_f is a run tree for each of the automata. Consequently, the if-direction of the above lemma implies that equation (i) corresponding to the automaton \mathcal{A}_i has a solution θ_i such that $q_f\theta_i(X) = S(t)$. Since X is the only variable shared by the equations, and since the solutions θ_i coincide on X, there is a substitution θ that solves the equations (i) simultaneously.

Now, assume that θ solves all the equations (i). The only-if direction of the above lemma implies that, for each automaton \mathcal{A}_i , the set $q_f\theta(X)$ is a union of run tree sets. Consequently, for each $i, 1 \leq i \leq n$, there exist run trees $t_{i,1}, \ldots, t_{i,m_i}$ for \mathcal{A}_i such that $q_f\theta(X) = S(t_{i,1}) \cup \ldots \cup S(t_{i,m_i})$. Since the leaves of the trees $t_{i,j}$ are all labeled with q_f , we know that the corresponding trees $t_{i,j}^{\sharp}$ are accepted by \mathcal{A}_i . The remaining obstacle is that the set $q_f\theta(X)$ can be represented as the union of many different tree sets, and thus it is not clear that the same tree is accepted by all the automata. This obstacle is obviously overcome by the following lemma, which depends on the fact we consider deterministic root-to-frontier automata.

Lemma 15 Let t_1, \ldots, t_m be run trees for the drfa \mathcal{A} , and let t be a tree. If $S(t) \subseteq S(t_1) \cup \ldots \cup S(t_m)$, then t is also a run tree for \mathcal{A} .

Proof. We consider a node κ in t immediately above the leaves. Let f be the label of this node, and assume that f is of rank k. Thus, S(t) contains the words $q_1 1 f u, \ldots, q_k k f u$ for a word u and states q_1, \ldots, q_k of \mathcal{A} . Since $S(t) \subseteq S(t_1) \cup \ldots S(t_m)$, each word $q_j j f u$ is contained in a set $S(t_{i_j})$ for $i_j \in \{1, \ldots, m\}$. Let κ_j be the node in t_{i_j} corresponding to f u. Let f u be the run of f u on f u, and let f u determined by a run of a drfa to the nodes on a path from the root to a leaf are uniquely determined by the labels of the nodes on this path, we know that f u determined by the labels of the nodes on this path, we know that f u determined by the fact that the trees f u is deterministic, we can deduce f u determined by the fact that the trees f u is deterministic, we can deduce f u determined by the fact that the trees f u is deterministic, we can deduce f u determined by the fact that the trees f u is deterministic. Since this argument applies to all nodes in f u immediately above the leave, we have shown that f u is in fact a run tree.

To sum up, we have shown that the intersection problem for deterministic root-to-frontier automata, which is known to be Exptime-hard, can be reduced to solving a system of linear equations over sets of finite words. This proves

 $^{^{7}\}mathrm{By}$ our assumptions on the automata, no trees consisting of a root that is itself a leaf can be accepted.

Theorem 16 Solvability of ACUIh-unification problems is Exptime-hard.

Consequently, solvability of ACUIh-unification problems and unifiability of \mathcal{FL}_0 -concept terms are Exptime-complete problems.

7 ACUIh-matching is polynomial

For the purpose of this article, where we are only interested in the existence of matchers, matching can be seen as the special case of unification where the term t on the right-hand side of the equation s = t does not contain variables [9]. As for unification, we can restrict our attention to the case of a single such equation.

As an easy consequence of Theorem 7 we obtain that matching of \mathcal{FL}_0 -concept terms (equivalently, ACUIh-matching) can be reduced to solving linear equations of the form

$$S_0 \cup S_1 X_1 \cup \dots \cup S_n X_n = T_0, \quad (***)$$

where S_0, \ldots, S_n, T_0 are finite sets of words over the alphabet of all role names. A solution of this equation assigns finite sets of words to the variables X_i such that the equation holds.

Lemma 17 Equation (***) has a solution iff the following is a solution of (***):

$$\theta(X_i) := \bigcap_{u \in S_i} u^{-1} T_0 \quad (i = 1, \dots, n).$$

Proof. The if-direction is trivial. To show the only-if-direction, we assume that $\tau(X_1), \ldots, \tau(X_n)$ are finite sets of words that solve (***).

First, we prove that $\tau(X_i) \subseteq \theta(X_i)$ holds for all i = 1, ..., n. Thus, let $v \in \tau(X_i)$ and $u \in S_i$. Since $S_i\tau(X_i) \subseteq T_0$, we know that $uv \in T_0$, and thus $v \in u^{-1}T_0$. This shows that $\tau(X_i) \subseteq u^{-1}T_0$ for all $u \in S_i$, which yields $\tau(X_i) \subseteq \theta(X_i)$.

As an immediate consequence, we obtain

$$T_0 = S_0 \cup S_1 \tau(X_1) \cup \cdots \cup S_n \tau(X_n) \subseteq S_0 \cup S_1 \theta(X_1) \cup \cdots \cup S_n \theta(X_n).$$

It remains to be shown that the other inclusion holds as well. Obviously, we have $S_0 \subseteq T_0$ since there exists a solution. To conclude the proof, let $u \in S_i$ and $v \in \theta(X_i)$. We must show that $uv \in T_0$. By definition of $\theta(X_i)$, we know that $v \in u^{-1}T_0$, and thus $uv \in T_0$.

Obviously, computing the sets $\theta(X_i)$ and checking whether they yield a solution of (***) can be done in time polynomial in the size of (***). Thus, we have proved the following theorem:

Theorem 18 Solvability of ACUIh-matching problems can be decided in polynomial time.

Consequently, matching of \mathcal{FL}_0 -concept terms is also polynomial.

The connection to the work of Borgida and McGuinness

In [7], Borgida and McGuinness consider a slightly different matching problem: matching modulo subsumption. For given concept terms C and D, where C does not contain variables, they ask for a substitution σ such that $C \sqsubseteq \sigma(D)$. Moreover, they are interested in a substitution σ such that $\sigma(D)$ is as small as possible w.r.t. the subsumption hierarchy.

Obviously, since C does not contain variables, $C \sqsubseteq \sigma(D)$ iff $\sigma(C \sqcap D) = C \sqcap \sigma(D) \equiv C$, which shows that matching modulo subsumption can be reduced to matching as considered above. In particular, this shows that for \mathcal{FL}_0 -concept terms matching modulo subsumption is polynomial:

Corollary 19 The following problem is decidable in polynomial time:

Instance: \mathcal{FL}_0 -concept terms C and D, where C does not contain variables.

Question: Does there exist a substitution σ such that $C \sqsubseteq \sigma(D)$?

As an easy consequence of the proof of Lemma 17, we can also compute a substitution σ such that $\sigma(D)$ is as small as possible w.r.t. the subsumption hierarchy, if the matching problem is solvable. In fact, we have shown that the solution θ of (***) constructed in the proof is larger (w.r.t. set inclusion) than all other solutions of (***). Since each word in a solution of (***) gives rise to an additional value restriction, it is clear that the largest solution of (***) gives rise to a solution σ of the matching problem such that $\sigma(D)$ is as small as possible w.r.t. subsumption.

Borgida and McGuinness consider a language that is more expressive than \mathcal{FL}_0 . In addition, they allow for role variables (which may be replaced by role constants). They present a polynomial matching algorithm, which is, however, not complete. In addition they state (without proof) that matching for \mathcal{FL}_0 -concept terms containing role variables is NP-complete. This result can easily be proved as follows:

Theorem 20 Solvability of matching problems for \mathcal{FL}_0 -concept terms containing role variables is NP-complete.

Proof. Since role variables may only be replaced by role constants (and not by complex role terms), we can nondeterministically guess the right assignment of role names to role variables, and then apply our polynomial decision procedure for matching of \mathcal{FL}_0 -concept terms without role variables. This shows that the problem is in NP.

To show the hardness result, we reduce monotone 1-in-3-SAT (see [10]) to the matching problem for \mathcal{FL}_0 -concept terms containing role variables. For every propositional variable p in an instance of monotone 1-in-3-SAT we introduce a role variable R_p . In addition, we use role constants R_0 and R_1 to represent the truth values. A clause $p \vee q \vee r$ is translated into the matching problem

$$\forall R_n. \forall R_q. \forall R_r. A \cap X = \forall R_0. \forall R_0. \forall R_1. A \cap \forall R_0. \forall R_1. \forall R_0. A \cap \forall R_1. \forall R_0. \forall R_0. A,$$

where X is a concept variable used only in this equation. It is easy to see that a solution of this problem assigns R_1 to exactly one of the three role variables R_p, R_q, R_r , and R_0 to the other two. Vice versa, any such assignment can be extended to a solution of the matching problem by assigning an appropriate value to X. Thus, the system of all matching problems obtained from the clauses of the instance of monotone 1-in-3-SAT is solvable iff the monotone 1-in-3-SAT problem has a solution. Since solving systems of matching problems can be reduced to solving a single matching problem, this reduction also shows NP-hardness for single matching problems.

8 Future work

The main topic for future work is to extend the decidability results for unification and matching to more expressive DL languages. Using a direct reduction of the unification problem to a corresponding formal language problem (as described in the previous section), our approach may also be applicable to languages for which equivalence of concept terms is not axiomatizable by a commutative equational theory.

Another interesting problem is how to define an appropriate ordering on unifiers. For the instantiation preorder usually employed in unification theory, ACUIh is not well-behaved [1]: it is not possible to represent all unifiers by finitely many most general ones. However, note that a more expressive language might lead to a theory with a better behaviour (since in a richer signature there are more substitutions available). Second, it might well be the case that the instantiation ordering on substitutions (which is appropriate for the applications of equational unification in theorem proving, term rewriting, and logic programming) is not the right ordering to use when dealing with substitutions operating on concept terms. As indicated by the work of Borgida and McGuinness [7], another ordering, induced by the subsumption hierarchy, might be more appropriate.

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