



Faculty of Computer Science Chair of Automata Theory

INTRODUCTION TO NONMONOTONIC REASONING

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About the Course

Course Material

- Book "Nonmonotonic Reasoning" by Grigoris Antoniou
- Book "Nonmonotonic Reasoning" by G. Brewka, J. Dix, K. Konolige
- available on course website:
 - Slides
 - Exercise Sheets
- Things written on the blackboard

Contact Information

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- course web page: https://lat.inf.tu-dresden.de/teaching/ws2017-2018/NMR/

Exams Oral exams at the end of the semester or during semester break

Section 1

Introduction

A non-technical one!

Nonmonotonic Reasoning

is a long-standing area of knowledge representation and thus of AI

Classical Logic

is monotone in the following sense: Whenever a formula φ is a logical consequence of a set of formulas T, then φ is also a logical consequence of an arbitrary superset of T.

Common sense reasoning

works differently:

We draw plausible conclusions based on the assumption the world is normal and works as expected.

Best we can do under incomplete information.

Sometimes the normality assumption goes wrong.

Nonmonotonic Reasoning

: additional information may invalidate conclusions drawn earlier

An Example

Assume you want to meet Prof. Petterson.

She usually is in the CS building in the afternoon.

You assume that this is the case today and go to the CS department in the afternoon.

Many people stand in front of the building—a while ago a fire alarm has gone off.

This new piece of information invalidates the normality assumption and so the conclusion about the present location of Prof. Petterson, too!

Major Application Problems

Databases

Suppose we want to build a DB about airline flights

- put positive facts: "Flight from DRS to LHR, by StarAir, 8.00 am, Oct. 12th"
- assumption: DB contains all relevant facts
 - impossible to put all negative facts!
 - inconvenient for updates!
- solution proposed by R. Reiter '78: capture the assumption formally Closed world assumption (CWA)

Major Application Problems

Puzzles

- e.g. "Missionaries and cannibals":
 3 missionaries and 3 cannibals come to a river. A row boat with 2 seats is available. If the cannibals outnumber the missionaries, on a bank of the river, the missionaries will be eaten. How shall they cross the river?
- easy: stating positive facts, e.g. "the boat carries 2 people."
- difficult: stating negative assumptions, e.g. "the river can only be crossed by boat."
- formal approach for dealing with unstated assumptions: circumscription by J. McCarthy

Major Application Problems

Diagnosis

- Diagnosis is a nonmonotonic task!
- Suppose an emergency case is brought in. The doctor treats the patient immediately without knowing the cause of the symptoms → makes assumptions about the "most plausible" and "worst possible" cause.
- Reasoning task: find "most plausible cause" of the problem

Natural language understanding

- natural language is ambiguous → competing interpretations
- if choice was wrong, working hypothesis may be revised
- nonmonotonic reasoning provides mechanisms to support these operations

Legal reasoning

- Most legal regulations are rules with exceptions
- defaults can represent this naturally

Rules with exceptions

Most rules we use in commonsense reasoning such as:

"Professors teach." "Birds fly." "Well tested software is reliable."

describe what normally holds, but not necessarily without exception.

This is in contrast to formulas in first order logic:

 $\forall x (prof(x) \longrightarrow teaches(x))$ $\forall x (bird(x) \longrightarrow flies(x))$ $\forall x (Software(x) \land well-tested(x) \longrightarrow reliable(x))$

To apply such a rule we need to know whether the concrete instance is exceptional. How to derive this?

The Frame Problem

- To express effects of actions (and reason about changes they cause), one has to indicate under what circumstances a proposition whose truth value may vary does hold.
- E.g. in situation calculus, effects of actions can easily be described. It is more problematic to describe what does not change when an event occurs.
- The frame problem asks how to represent the large amount of non-changes when reasoning about action.

Idea: use a persistence rule such as

"what holds in a situation typically holds in the situation after an action was performed, unless it contradicts the description of the effects of the action."

This rule is nonmonotonic!

• The frame problem has provided a major impetus to research of nonmonotonic reasoning

Overview of the lecture

Main topics

Default logic Autoepistemic Logic Circumscription Nonmonotonic inference rules Belief Revision

Default Logics

- introduced by Ray Reiter in 1980
- default logics distinguish: axioms (or facts) from rules of thumb called defaults E.g.:

 $\frac{bird(x):flies(x)}{flies(x)}$

- default theory:
 - set of facts: certain, but incomplete information about the world
 - set of defaults: sanction plausible but not necessarily true conclusions
- reasoning under the closed world assumption
- operational semantics by extensions (:beliefs that may hold about the domain)
- Goal: compute sets of acceptable beliefs
- variants of default logics

Autoepistemic Logics (AEL)

- proposed by Robert C. Moore in 1985
- "autoepistemic": reflection upon self-knowledge
- AELs can express the lack of facts
- an ideally rational agent forms belief sets given initial assumption
- closely related to Modal logics
- emphasis on inference relations
- compute expansions specifies which formulas are true and which ones are false
- computation of set of preferred models (≈ "normal models"): minimization of the extension of some predicates New information changes this set!
- computational properties
- relation to default logic

Circumscription

- introduced by John McCarthy objective: formalize common sense reasoning used in dealing with everyday problems
- Refined and formalized by Vladimir Lifschitz
- implicit assumption of inertia: things do not change unless otherwise specified.
- also based on preferred models (minimizing the extent of some predicates)
- computational properties
- relation to default logic

Belief Revision

- investigated by Alchourrón, Gärdenfors, Makinson
- provides operations to model change
- inconsistent knowledge: which facts to give up, which to keep?
- computational model: change of finite theory basis and iterated revision
- minimality principle, AGM postulates
- computational properties

Nonmonotonic inference rules

- orthogonal view: which postulates should a "good" nonmonotonic inference rule fulfill?
- interaction of logical connectives
- preferential models
- formal properties of inference rules

Section 2

Preliminaries

A technical brush-up!

First Order Logic (FOL) a.k.a. Predicate logic

Predicate logic

- is a classical monotone logic
- basis for the approaches discussed in this lecture

Syntax of First Order Logic

Symbols:

- special characters:
 ∧ (conjunction), ∨ (disjunction), ¬ (negation),
 → (implication), ↔ (equivalence),
 ∃ (existential quantifier), ∀ (universal quantifier),
 (,),
 V₁, ..., V_n (countable set of variables)
- signature Σ

Intuitively, $\boldsymbol{\Sigma}$ contains the predicate symbols, function symbols each associated with an arity.

E.g.: $\Sigma = \{(+, 3), (inc, 1), \dots\}$

A function symbol of arity 0 is called a constant.

A predicate symbol of arity 0 is called an atom (or proposition).

Syntax of First Order Logic: Terms

(Consider a fixed signature Σ .)

Definition 2.1 (Terms)

FOL terms are defined as:

- Every variable or constant is a term.
- If f is a function of arity n and t_1, \ldots, t_n are terms, then $f(t_1, \ldots, t_n)$ is a term.
- There is no other way of building terms.

A term is called ground iff¹ it does not contain any variables.

Syntax of First Order Logic: FOL Formulas

Definition 2.2 (Formulas)

Let *p* be a predicate symbol of arity *n*, t_1, \ldots, t_n are terms, φ and ψ be formulas and *X* be a variable. FOL formulas are defined as:

- $p(t_1, \ldots, t_n)$ is an (atomic) formula
- the following are (complex) formulas:

$$\begin{array}{l} - \neg \varphi \\ - (\varphi \lor \psi) \end{array}$$

$$- (\varphi \land \psi)$$

$$- \quad (\varphi \longrightarrow \psi)$$

$$- (\varphi \longleftrightarrow \psi)$$

$$\begin{array}{l} - (\exists X\varphi) \\ - (\forall X\varphi) \end{array}$$

- (∇, φ)
- There is no other way of building formulas.

If in $p(t_1, \ldots, t_n)$ all terms t_i $(1 \le i \le n)$ are ground, then $p(t_1, \ldots, t_n)$ is a ground atomic formula.

If Σ does contain only atoms (propositions!) and there are no variables in a formula φ , then φ is a formula of propositional logic.

NB: We may omit occasionally parentheses.

Syntax of First Order Logic: parts of formulas, kinds of variables

A term t' is a subterm of a term t, if it is a sub-string of t.

For an occurrence of $\forall X \varphi$ or $\exists X \varphi$ within a formula ψ , φ is the scope of the quantification $\forall X \varphi$ resp. $\exists X \varphi$.

An occurrence of a variable X in a formula ψ is called bound iff it is included in the scope of a quantification $\forall X$ or $\exists X$; otherwise the variable is free.

The variables for which there exists at least one free occurrence in a formula ψ are the free variables in ψ .

A formula is closed if it has no free variables, otherwise it is open.

Closed formulas are called sentences.

For every open formula ψ we define $\forall(\psi)$, the universal closure of ψ , to be the formula

 $\forall X_1 \dots \forall X_n \psi$, where X_1, \dots, X_n are all the free variables in ψ .

(Existential closure is defined analogously.)

A literal *L* is either an atomic formula (positive literal) or its negation (negative literal).

Auxiliary sets

We define the following auxiliary sets:

 N_{Var} is the set of all variables N_{Pred} is the set of all predicates N_{Func} is the set of all relations N_{Pred}^{Σ} is the subset of all predicates in a given Σ , i.e., $N_{Pred}^{\Sigma} = N_{Pred} \cap \Sigma$ N_{Func}^{Σ} is the subset of all relations in a given Σ , i.e., $N_{Func}^{\Sigma} = N_{Func} \cap \Sigma$ Substitutions ... in terms What to do with variables?

Definition 2.3 (Substitution) A substitution σ is a finite set { $X_1/t_1, \ldots, X_n/t_n$ } s.t.² $X_1 \ldots, X_n$ are different variables, and t_i is a term different from X_i (for all $1 \le i \le n$).

If all terms are ground, then σ is a ground substitution.

Intuition:

The result of applying a substitution σ to a term t (denoted $t\sigma$) is replacing all occurrences of X_i in t by t_i simultaneously.

For example:

Let $\sigma_{ex} = \{V_1/p'(), V_2/q(V_1), V_3/q'(V_2, p'())\}$ and $t = p(V_2, f(V_1, V_2), V_3)$, then $t\sigma = p(q(V_1), f(p'(), q(V_1), q'(V_2, p'())))$ $(t\sigma)\sigma = p(q(p'()), f(p'(), q(p'()), q'(q(V_1), p'())))$ $((t\sigma)\sigma)\sigma = p(q(p'()), f(p'(), q(p'()), q'(q(p'()), p'())))$

²abbreviation for "such that"

Substitutions ... in formulas

Lifting substitutions to formulas:

The result of applying a substitution σ to a formula φ (denoted $\varphi \sigma$) is replacing all free occurrences of X_i in φ by t_i .

 $\varphi\sigma$ is a ground instance of φ , if $\varphi\sigma$ contains no free variables.

 $\varphi\sigma$ is admissible, if none of the variables of any t_i becomes bound after σ has been applied to ϕ .

Semantics of FOL

Definition 2.4 (Interpretation)

An interpretation ${\mathcal I}$ consists of

- a non-empty set $dom(\mathcal{I})$ the interpretation domain (or universe),
- a function $f^{\mathcal{I}} : dom(\mathcal{I})^n \longrightarrow dom(\mathcal{I})$ for every function symbol f of arity n.
- a relation $p^{\mathcal{I}} \subseteq dom(\mathcal{I})^n$ for every predicate symbol *p* of arity *n*.

For example:

we can model the mathematical concept of graphs as a pair G = (V, E), where V is the interpretation domain of vertices and E is the binary edge relation.

Semantics of FOL

The state over an interpretation \mathcal{I} is a function $sta : N_{Var} \longrightarrow dom(\mathcal{I})$.

Given: variable X and value $a \in dom(\mathcal{I})$. The modified state, where X is substituted by a sta [X/a] is as function sta, but now X is assigned to a.

Definition 2.5 (Value of a term)

Given an interpretation \mathcal{I} and a state *sta*. Then the value of a term *t* is defined inductively as:

- $val_{\mathcal{I},sta}(X) = sta(X)$
- $val_{\mathcal{I},sta}(f(t_1,\ldots,t_n)) = f^{\mathcal{I}}(val_{\mathcal{I},sta}(t_1),\ldots,val_{\mathcal{I},sta}(t_n)).$

Semantics of FOL formulas

Definition 2.6

Given: an interpretation \mathcal{I} and a state *sta*.

We define when a formula φ is true in \mathcal{I} and *sta* (denoted $\mathcal{I} \models_{sta} \varphi$), inductively:

- $\mathcal{I} \models_{sta} p(t_1, \ldots, t_n)$ iff $(val_{\mathcal{I},sta}(t_1), \ldots, val_{\mathcal{I},sta}(t_n)) \in p^{\mathcal{I}}$
- $\mathcal{I} \models_{sta} \neg \psi$ iff $\mathcal{I} \not\models_{sta} \psi$
- $\mathcal{I} \models_{sta} (\psi_1 \lor \psi_2)$ iff $\mathcal{I} \models_{sta} \psi_1$ or $\mathcal{I} \models_{sta} \psi_2$
- $\mathcal{I} \models_{sta} (\psi_1 \land \psi_2)$ iff $\mathcal{I} \models_{sta} \psi_1$ and $\mathcal{I} \models_{sta} \psi_2$
- $\mathcal{I} \models_{sta} (\psi_1 \longrightarrow \psi_2)$ iff $\mathcal{I} \models_{sta} (\neg \psi_1 \lor \psi_2)$
- $\mathcal{I} \models_{sta} (\psi_1 \longleftrightarrow \psi_2)$ iff $\mathcal{I} \models_{sta} (\psi_1 \land \psi_2)$ or $\mathcal{I} \models_{sta} (\neg \psi_1 \land \neg \psi_2)$
- $\mathcal{I} \models_{sta} \forall X \psi$ iff $\mathcal{I} \models_{sta[X/a]} \psi$ for all $a \in dom(\mathcal{I})$
- $\mathcal{I} \models_{sta} \exists X \psi$ iff there is an $a \in dom(\mathcal{I})$ s.t. $\mathcal{I} \models_{sta[X/a]} \psi$

Note: state *sta* is irrelevant, if the formula is ground. The truth-value depends only on \mathcal{I} .

Model, validity of FOL formulas

Definition 2.7 (valid, model)

A FOL formula φ is valid (or true) in \mathcal{I} , if $\mathcal{I} \models \varphi$ for all states over \mathcal{I} . In this case \mathcal{I} is a model of φ (denoted $\mathcal{I} \models \varphi$).

Lifting this to sets of formulas:

 \mathcal{I} is a model of a set of formulas M ($\mathcal{I} \models M$), iff it is a model of each formula in M.

A set of formulas M' follows (logically) from a set of formulas M (denoted $M \models M'$) iff every model of M is also a model of M'.

Definition 2.8 (Deductive closure, theory)

Let *M* be a set of formulas. Th(M) denotes the set of all formulas that follow from *M* (called the deductive closure of *M*). If M = Th(M), then *M* is called deductively closed. A deductively closed set of closed formulas is called a Theory. Reasoning in FOL

Definition 2.9 (Tautology, satisfiable)

A formula is a tautology (or valid), iff it is valid in every interpretation.

True or \top denote tautologies. *False* and \perp denote negations of tautologies.

A formula φ is satisfiable iff there is an interpretation \mathcal{I} and a state *sta* s.t. $\mathcal{I} \models_{sta} \varphi$. A set of formulas M is satisfiable iff there is an interpretation \mathcal{I} and a state *sta* s.t. $\mathcal{I} \models_{sta} M$.

The formulas φ and ψ are equivalent iff $\varphi \longleftrightarrow \psi$ is a tautology.

A set of formulas *M* is consistent iff *M* is satisfiable. A formula φ is consistent with *M* iff $M \cup \{\varphi\}$ is consistent.

Normal forms

A FOL formula is in ...

Prenex normal form

if it has the form $Q_1 X_1 \cdots Q_n X_n \varphi$, where Q_i are quantifiers, X_i are variables, and φ a formula not containing any quantifiers.

Conjunctive normal form (CNF)

if it has the form $\bigwedge_{i=1}^{n} \bigvee_{j=1}^{m} L_{ij}$ with literals L_{ij} .

- Disjunctive normal form (DNF)
- if it has the form $\bigvee_{i=1}^{n} \bigwedge_{j=1}^{m} L_{ij}$ with literals L_{ij} .
- Skolem normal form

if it has the form $\forall X_1 \cdots \forall X_n \varphi$, where φ is a quantifier-free formula in CNF.

Herbrand interpretation

Definition 2.10 (Herbrand interpretation)

A Herbrand interpretation is an interpretation \mathcal{I} with the following properties:

- 1. $dom(\mathcal{I})$ is the set of all ground terms.
- 2. Function symbols are interpreted in a fixed way:

$$f^{\mathcal{I}}(t_1,\ldots,t_n)=f(t_1,\ldots,t_n)$$

for ground terms t_1, \ldots, t_n .

Not fixed in a Herbrand interpretation: interpretation of the predicate symbols. Herbrand interpretations can be represented as a set of ground literals. Two important theorems

Herbrand's Theorem

Let *M* be a set of formulas of the form $\forall X_1 \dots \forall X_n \psi$ with a quantifier-free formula ψ . The set of formulas ground (M) is defined as the set of formulas obtained by $\psi[X_1/t_1, \dots, X_n/t_n]$, where the t_i are arbitrary ground terms.

According to Herbrand's Theorem the following statements are equivalent:

- *M* has a model
- *M* has a Herbrand model
- ground(M) has a model
- ground(M) has a Herbrand model

Compactness Theorem

The compactness theorem says that a set of *M* of formulas is satisfiable iff every finite subset of *M* is satisfiable.