

# Abductive Differences of Quantified ABoxes

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# Quantified ABoxes

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- A *quantified ABox*  $\exists X.A$  consists of
  - a finite set  $X$  of *variables* and
  - an  $\mathcal{EL}$  ABox  $A$ , called *matrix*, in which variables may be used in place of individuals.
- We assume every quantified ABox be in normal form, i.e. no complex concepts occur in the matrix.

**Example.**  $\exists \emptyset.\{i : (A \sqcap \exists r.B), j : \top\}$  and  $\exists \{x\}.\{i : A, (i, x) : r, x : B\}$  are equivalent, but only the latter is in formal form.

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- The semantics is defined by models and variable assignments:  
 $\mathcal{I} \models \exists X.A$  iff. there is  $\mathcal{Z} : X \rightarrow \text{Dom}(\mathcal{I})$  such that  $\mathcal{I}[\mathcal{Z}] \models A$ .

## Quantified ABoxes

- Over signatures consisting of constants, unary predicates, and binary predicates only, the following are syntactic variants of each other, i.e. semantically the same:
  - relational structures with constants,
  - databases with nulls,
  - primitive-positive (pp) formulas in first-order logic,
  - conjunctive queries (CQs), and
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- Most importantly:  $\exists X.\mathcal{A} \models \exists Y.\mathcal{B}$  iff. there is a homomorphism from  $\exists Y.\mathcal{B}$  to  $\exists X.\mathcal{A}$ .  
Recall: a *homomorphism* from  $\exists X.\mathcal{A}$  to  $\exists Y.\mathcal{B}$  is a mapping  $h : \text{Obj}(\exists X.\mathcal{A}) \rightarrow \text{Obj}(\exists Y.\mathcal{B})$  that fulfills the following conditions:
  - 1  $h(i) = i$  for each individual  $i$ ,
  - 2 if  $t : A \in \mathcal{A}$ , then  $h(t) : A \in \mathcal{B}$ ,
  - 3 if  $(t, u) : r \in \mathcal{A}$ , then  $(h(t), h(u)) : r \in \mathcal{B}$ .

# Explaining Observations by Abductive Differences



## Observations and Explanations

**Definition.** Consider two quantified ABoxes:

- an observation  $\exists X.A$
- and a knowledge base  $\exists Y.B$ .

An *abductive difference* (or *explanation*) of  $\exists X.A$  w.r.t.  $\exists Y.B$  is a quantified ABox  $\exists Z.C$  such that  $\exists Y.B \cup \exists Z.C \models \exists X.A$ .

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### Example.

- Observation:  $\exists\{x\}.\{\text{tom} : \text{Cat}, (\text{tom}, x) : \text{chases}, x : \text{Mouse}\}$
- Knowledge base:  $\exists\emptyset.\{\text{tom} : \text{Cat}, \text{jerry} : \text{Mouse}\}$
- Two minimal explanations:  $\exists\{x\}.\{(\text{tom}, x) : \text{chases}, x : \text{Mouse}\}$   
and  $\exists\emptyset.\{(\text{tom}, \text{jerry}) : \text{chases}\}$

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## How can we compute all minimal abductive differences?

## Lower Bound

**An observation can have at least exponentially many explanations.**

**Example.** For each number  $n \geq 1$ , consider

- the observation  $\exists\{x_1, \dots, x_n\}. \{(x_1, x_2) : r, (x_2, x_3) : r, \dots, (x_{n-1}, x_n) : r, x_1 : A_1, \dots, x_n : A_n\}$
- and the knowledge base  $\exists\emptyset. \{(i, i) : r, (j, j) : r, (i, j) : r, (j, i) : r\}$ .

Then, in order to obtain a minimal explanation, we can choose between  $i : A_\ell$  and  $j : A_\ell$  for each  $\ell \in \{1, \dots, n\}$ , i.e. every qABox  $\exists\emptyset. \{t_1 : A_1, \dots, t_n : A_n\}$  with  $t_\ell \in \{i, j\}$  is a minimal explanation. Thus there are at least  $2^n$  minimal explanations.

## Partial Homomorphisms

Consider an observation  $\exists X.A$ , a knowledge base  $\exists Y.B$ , and an explanation  $\exists Z.C$ .

Then  $\exists Y.B \cup \exists Z.C \models \exists X.A$

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We split  $h$  into two mappings:

- 1  $p$  is the part of  $h$  that maps to objects of the knowledge base  $\exists Y.B$ ,
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$p$  is a partial function from  $\text{Obj}(\exists X.A)$  to  $\text{Obj}(\exists Y.B)$  that pinpoints the part of the observation that is already known.

We call  $p$  a *partial homomorphism* from  $\exists X.A$  to  $\exists Y.B$  (see paper for details).

This notion is independent from the particular explanation  $\exists Z.C$  and the part  $q$ .

**All minimal abductive differences can be obtained from these partial homomorphisms.**



## $p$ -Differences

For each partial homomorphism  $p$  from the observation  $\exists X.A$  to the knowledge base  $\exists Y.B$ , we can construct the  $p$ -difference  $\exists X.A \setminus^p \exists Y.B$ .

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$p$ -differences are canonical:

- 1  $p$  can be extended to a homomorphism from  $\exists X.A$  to  $\exists Y.B \cup (\exists X.A \setminus^p \exists Y.B)$ .

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Thus, every  $p$ -difference is an abductive difference.
- 2 Each explanation entails some  $p$ -difference.  
Thus, every minimal explanation is equivalent to a  $p$ -difference.

**Theorem.** Up to equivalence, each minimal explanation has polynomial size and the set of all minimal explanations can be computed in exponential time.

# Outlook

## Implementation and Evaluation

There is a correspondence between

- partial homomorphisms from  $\exists X.A$  to  $\exists Y.B$
- and homomorphisms from  $\exists X.A$  to an extension of  $\exists Y.B$ .

Thus, partial homomorphisms can be enumerated with off-the-shelf query-answering systems.

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Interesting future work:

- Implementation
- Evaluation with real-world datasets

## Taking Ontologies into Account

(Minimal) abductive differences can also be considered w.r.t. ontologies. An observation can then have infinitely many non-equivalent explanations, and their sizes are not bounded.

**Example.** Consider

- the observation  $\{\text{alice} : \text{Human}\}$
- and the KB consisting of the  $\mathcal{EL}$  ABox  $\{\text{bob} : \text{Human}\}$  and the  $\mathcal{EL}$  ontology  $\{\exists \text{hasParent}.\text{Human} \sqsubseteq \text{Human}\}$ .

For each number  $n > 0$ , the qABox  $\exists\{x_1, \dots, x_n\}.\{(\text{alice}, x_1) : \text{hasParent}, (x_1, x_2) : \text{hasParent}, \dots, (x_{n-1}, x_n) : \text{hasParent}, (x_n, \text{bob}) : \text{hasParent}\}$  is a minimal abductive difference.

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Interesting future work:

- Enumeration of all minimal explanations
- Use of practically motivated metrics to restrict and compare explanations
- User interaction to pinpoint one practically useful explanation